#### Announcements

## **Basic Ray Tracing**



Readings: Chapter 4

Some slides courtesy of Steven Marschner

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# • HW3 due on the 8th (this Wed.)

- Will have a ray-tracer exercise next class.
   Please check it out by tomorrow morning.
- Lecture by Yuval Boger (CEO), Sensics on 4/27 (Optional)

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## What is ray tracing?



http://www.ics.uci.edu/~gopi/CS211B/Ray Tracing%20tutorial.pdf

#### Render images with computers.

Physically correct images are composed by light and that light will usually come from a light source and bounce around as light rays in a scene before hitting our eyes or a camera. By being able to reproduce in computer simulation the path followed from a light source to our eye, we should be able to determine what our eyes see.

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## **Objectives**

- Learn the basic ray tracer
  - When to use it
  - How to do it in OpenGL
  - What are these techniques
- Resources:
  - <u>https://www.siggraph.org/education</u> /materials/HyperGraph/raytrace/rtr ace0. htm
  - <u>(better in my opinion) http</u>
     <u>://www.ics.uci.edu/~gopi/CS211B/R</u>
     <u>ayTracing</u>
     <u>%20tutorial.pdf</u>

## High-level idea

- Find the color of each pixel on the view window.
- E.g., if our image resolution is 640x480, we'd break up the view window into a grid of 640 squares across and 400 square down. Ray tracer is to assign colors to these points.



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 Tracing rays from the light source to the eye. Lots of rays are wasted because they never reach the eye.



 We trace a new ray from each ray-object intersection directly towards the light source



http://www.cs.unc.edu/~rademach/xroads-RT/RTarticle.html#glas90

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## Ray tracing idea



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## Ray tracing algorithm



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## Generate eye rays

 Use window analogy directly



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## Generate eye rays orthographic

#### Positioning the view rectangle

- Establish three vectors to be camera basis: u, v, w
- View rectangle is in u-v plane, specified by I, r, t, b



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## Generating eye rays - perspective

- Compute s in the same way; just substract dw
  - Coordinates of s are (u, v, -d)



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## Pixel-to-image mapping

• One last detail: (u, v) coords of a pixel



## Ray intersection

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## Ray: a half line

• Standard representation: point p and direction d

#### $\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$

- this is a parametric equation for the line
- lets us directly generate the points on the line
- if we restrict to t > 0 then we have a ray
- note replacing **d** with a**d** doesn't change ray (a > 0)



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## Ray-sphere intersection: algebraic

Condition I: point is on ray

$$\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$$

Condition 2: point is on sphere
 Assume unit sphere:

$$\|\mathbf{x}\| = 1 \Leftrightarrow \|\mathbf{x}\|^2 = 1$$

$$f(\mathbf{x}) = \mathbf{x} \cdot \mathbf{x} - 1 = 0$$

$$J(\mathbf{x}) = \mathbf{x} \cdot \mathbf{x} - 1 = 0$$

- Substitute  $(\mathbf{p} + t\mathbf{d}) \cdot (\mathbf{p} + t\mathbf{d}) 1 = 0$ 
  - This is a quadratic equation in t

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## Ray-sphere intersection: algebraic

- Solution for t by quadratic formula:
  - Simpler from holds when d is a unit vector
  - But we won't assume this in practice
  - I will use the unit-vector form to make the geometric interpolation

$$t = \frac{-\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - (\mathbf{d} \cdot \mathbf{d})(\mathbf{p} \cdot \mathbf{p} - 1)}}{\mathbf{d} \cdot \mathbf{d}}$$
$$t = -\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$

## Ray-sphere intersection: geometric



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## **Ray-box intersection**

- Could intersect with 6 faces individually
- Better way: box is the intersection of 3 slabs



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## Ray-slab intersection

- 2D example
- 3D is the same!



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## Intersection intersection

- Each intersection is an interval
- Want last entry point and first exist point



## Ray-triangle intersection

- Condition I: point is on ray
   R(t) = p + t d
- Condition 2: point is on plane
   (x-a). n = 0
- Condition 3: point is on the inside of all three edges
- First solve 1 & 2 (ray-plane intersection)
  - Substitute and solve for t:

$$\begin{aligned} (\mathbf{p} + t\mathbf{d} - \mathbf{a}) \cdot \mathbf{n} &= 0 \\ t &= \frac{(\mathbf{a} - \mathbf{p}) \cdot \mathbf{n}}{\mathbf{d} \cdot \mathbf{n}} \end{aligned}$$

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## Ray-triangle intersection

 In plane, triangle is the intersection of 3 half spaces



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## Inside-edge test

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- Need outside vs. inside
- Reduce to clockwise vs. counterclockwise
- Vector of edge to vector to xUser cross product to decide



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## Ray-triangle intersection

$$\begin{split} (\mathbf{b}-\mathbf{a}) \times (\mathbf{x}-\mathbf{a}) \cdot \mathbf{n} &> 0\\ (\mathbf{c}-\mathbf{b}) \times (\mathbf{x}-\mathbf{b}) \cdot \mathbf{n} &> 0\\ (\mathbf{a}-\mathbf{c}) \times (\mathbf{x}-\mathbf{c}) \cdot \mathbf{n} &> 0 \end{split}$$



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## Image so far

• With eye ray generation and sphere intersection

Surface s = new Sphere((0.0, 0.0, 0.0), 1.0); for 0 <= iy < ny for 0 <= ix < nx { ray = camera.getRay(ix, iy); hitSurface, t = s.intersect(ray, 0, +inf) if hitSurface is not null image.set(ix, iy, white); }



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## Intersection against many shapes

The basic idea is

•

Group.intersect (ray, tMin, tMax) {
 tBest = +inf; firstSurface = null;
 for surface in surfaceList {
 httSurface, t = surface.intersect(ray, tMin, tBest);
 if hitSurface is not null {
 tBest = t;
 firstSurface = hitSurface;
 }
 }
 return hitSurface, tBest;
}

 this is linear in the number of shapes but there are sublinear methods (acceleration structures)

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## Image so far

 With eye ray generation and scene intersection



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## Shading

- 2D example
- 3D is the same!



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## Shading

- ٠ Compute light reflected toward camera
- ٠ Inputs:
  - -Eye direction
  - Light direction (for each of many lights) \_
  - Surface normal
  - Surface parameters (color, shininess,...)



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## **Diffuse reflection**

- · Light is scattered uniformly in all directions
  - The surface color is the same for all viewing directions
  - Lambert's cosine law

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Top face of cube receives a certain amount of light

Top face of 60° rotated cube intercepts half the light

In general, light per unit area is proportional to  $\cos \theta = \mathbf{I} \cdot \mathbf{n}$ 

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## Lambertian shading

٠ Shading independent of view direction



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}





### Shadows

- Surface is only illuminated if nothing blocks its view of the light
- With ray tracing it is easy to check
   Just intersect a ray with the scene
- Image so far

3

}

return black;

Surface.shade(ray, point, normal, light) {
 shadRay = (point, light.pos - point);
 if (shadRay not blocked) {
 v = -normalize(ray.direction);
 l = normalize(light.pos - point);
 // compute shading



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### Shadow rounding errors

 Don't fall victim to one of the classic blunders



- What is going on?
  - Hint: at what t does the shadow ray intersect the surface you're shading

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## Shadow rounding errors

- Solution shadow rays start a tiny distance from the surface
- Do this by moving the start point, or by limiting the t range



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## **Multiple lights**

- Important to fill in black shadows
- Just loop over lights add contributions
- Ambient shading
  - Black shadows are not really right
  - One solution: dim light at camera
  - Alternative: add a constant "ambient" color to the shading...
- Image so far
- shade(ray, point, normal, lights) {
   result = ambient;
   for light in lights {
   if (shadow ray not blocked) {
   result += shading contribution;
   }
   return result;
  }



## Specular shading (Blinn-Phong)

- Intensity depends on view direction
  - Bright near mirror configuration



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## **Diffuse reflection**

- Close to mirror <sub>≥</sub> half vector near normal
  - Measure "near" by dot product of unit vectors



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## Diffuse + Phong shading



## Ambient shading

- Shading that does not depend on anything
  - Add constant color to account for disregarded illumination and fill in black shadows



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## Putting it together

• Usually include ambient, diffuse, Phong in one model

$$\begin{split} L &= L_a + L_d + L_s \\ &= k_a I_a + k_d I \max(0, \mathbf{n} \cdot \mathbf{l}) + k_s I \max(0, \mathbf{n} \cdot \mathbf{h})^p \end{split}$$

 The final result is the sum over many lights

$$L = L_a + \sum_{i=1}^{N} [(L_d)_i + (L_s)_i]$$
  
$$L = k_a I_a + \sum_{i=1}^{N} [k_d I_i \max(0, \mathbf{n} \cdot \mathbf{l}_i) + k_s I_i \max(0, \mathbf{n} \cdot \mathbf{h}_i)^p]$$

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## Mirror reflection

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- Consider perfectly shiny surface
  - There is not a highlight
  - Instead there's a reflection of other objects
- Can render this using recursive ray tracing
  - To find out mirror reflection color, ask what color is seen from surface point in reflection direction
    - Already computing reflection direction for Phong...
  - "Glazed" material has mirror reflection and diffuse
  - L = La + Ld + Lm
  - Where Lm is evaluated by tracing a new ray

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## **Mirror reflection**



- Reflects incident light from mirror direction





## Ray tracer architecture 101

- You want a class called ray
  - Point and direction; evaluate (t)
  - Possible: tMin, tMax
- Some things can be intersected with rays
  - Individual surfaces
  - Groups of surfaces (acceleration goes here)
  - The whole scene
  - Make these all subclasses of surface
  - Limit the range of valid t values (e.g., shadow rays)
- Once you have the visible intersection, compute the color
  - may want to separate shading code from geometry
  - Separate class: material (each surface holds a reference to one)
  - Its job is to compute the color

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## Architectural practicalities

- Return values
  - Surface intersection tends to want to return multiple values
    - T, surface, normal vector; maybe surface point
  - Typical solution: an intersection record
    - A class with fields for all these things
    - Keep track of the intersection record for the closest intersection
    - Be careful of accidental aliasing
- Efficiency
  - What objects are created for every ray? Try to find a place for them where you can reuse them.
  - Shadow rays can be cheaper (any intersection will do, do not need closest)
  - But, "first get it right, then make it fast"