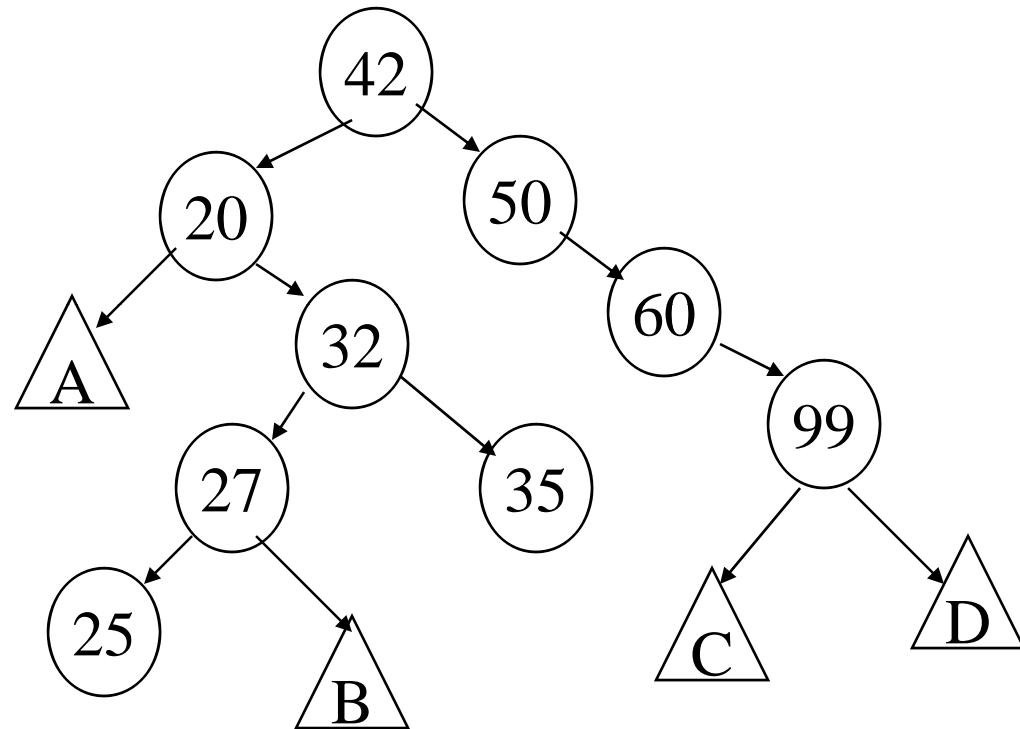

CMSC 341

Binary Search Trees

Binary Search Tree

- A ***Binary Search Tree*** is a Binary Tree in which, at every node v , the values stored in the left subtree of v are less than the value at v and the values stored in the right subtree are greater.
- The elements in the BST must be comparable.
- Duplicates are not allowed in our discussion.
- Note that each subtree of a BST is also a BST.

A BST of integers



Describe the values which might appear in the subtrees labeled A, B, C, and D

SearchTree ADT

■ The SearchTree ADT

- A *search tree* is a binary search tree which stores homogeneous elements with no duplicates.
- It is dynamic.
- The elements are ordered in the following ways
 - inorder -- as dictated by operator <
 - preorder, postorder, levelorder -- as dictated by the structure of the tree

BST Implementation

```
public class BinarySearchTree<AnyType extends Comparable<? super AnyType>>
{
    private static class BinaryNode<AnyType>
    {
        // Constructors
        BinaryNode( AnyType theElement )
        { this( theElement, null, null ); }

        BinaryNode( AnyType theElement,
                    BinaryNode<AnyType> lt, BinaryNode<AnyType> rt )
        { element = theElement; left = lt; right = rt; }

        AnyType element;           // The data in the node
        BinaryNode<AnyType> left; // Left child
        BinaryNode<AnyType> right; // Right child
    }
}
```

BST Implementation (2)

```
private BinaryNode<AnyType> root;

public BinarySearchTree( )
{
    root = null;
}

public void makeEmpty( )
{ root = null;
}

public boolean isEmpty( )
{
    return root == null;
}
```

BST “contains” Method

```
public boolean contains( AnyType x )
{
    return contains( x, root );
}

private boolean contains( AnyType x, BinaryNode<AnyType> t )
{
    if( t == null )
        return false;

    int compareResult = x.compareTo( t.element );

    if( compareResult < 0 )
        return contains( x, t.left );
    else if( compareResult > 0 )
        return contains( x, t.right );
    else
        return true;      // Match
}
```

Performance of “contains”

- Searching in randomly built BST is $O(\lg n)$ on average
 - but generally, a BST is not randomly built
- Asymptotic performance is $O(\text{height})$ in all cases

Implementation of printTree

```
public void printTree()
{
    printTree(root);
}

private void printTree( BinaryNode<AnyType> t )
{
    if( t != null )
    {
        printTree( t.left );
        System.out.println( t.element );
        printTree( t.right );
    }
}
```

BST Implementation (3)

```
public AnyType findMin( )
{
    if( isEmpty( ) ) throw new UnderflowException( );
        return findMin( root ).element;
}
public AnyType findMax( )
{
    if( isEmpty( ) ) throw new UnderflowException( );
        return findMax( root ).element;
}
public void insert( AnyType x )
{
    root = insert( x, root );
}
public void remove( AnyType x )
{
    root = remove( x, root );
}
```

The insert Operation

```
private BinaryNode<AnyType>
insert( AnyType x,  BinaryNode<AnyType> t )
{
    if( t == null )
        return new BinaryNode<AnyType>( x, null, null );

    int compareResult = x.compareTo( t.element );
    if( compareResult < 0 )
        t.left = insert( x, t.left );
    else if( compareResult > 0 )
        t.right = insert( x, t.right );
    else
        ; // Duplicate; do nothing
    return t;
}
```

The remove Operation

```
private BinaryNode<AnyType>
remove( AnyType x,  BinaryNode<AnyType> t )
{
    if( t == null )
        return t;    // Item not found; do nothing
    int compareResult = x.compareTo( t.element );
    if( compareResult < 0 )
        t.left = remove( x, t.left );
    else if( compareResult > 0 )
        t.right = remove( x, t.right );
    else if( t.left != null && t.right != null ){ // 2 children
        t.element = findMin( t.right ).element;
        t.right = remove( t.element, t.right );
    }
    else
        t = ( t.left != null ) ? t.left : t.right;
    return t;
}
```

Implementations of find Max and Min

```
private BinaryNode<AnyType> findMin( BinaryNode<AnyType> t )
{
    if( t == null )
        return null;
    else if( t.left == null )
        return t;
    return findMin( t.left );
}

private BinaryNode<AnyType> findMax( BinaryNode<AnyType> t )
{
    if( t != null )
        while( t.right != null )
            t = t.right;

    return t;
}
```

Average Case Analysis

- Internal Path Length, $D(N)$ =sum of the depths of all nodes in a tree with N nodes
- Consider a tree with the left subtree with i nodes and right subtree with $N-i-1$ nodes
- $D(N) = D(i) + D(N-i-1) + N - 1$

Replacing $D(i)$ and $D(N - i - 1)$ by the average internal path length

$$D(N) = \frac{2}{N} \sum_{j=0}^{N-1} D(j) + N - 1$$

$$D(1) = 0$$

Proof Sketch

Replacing $(N - 1)$ by cN where c is some constant

$$D(N) = \frac{2}{N} \sum_{j=0}^{N-1} D(j) + cN$$

$$ND(N) = 2 \sum_{j=0}^{N-1} D(j) + cN^2 \quad \text{--- Equation 1.}$$

Substituting $N - 1$ for N in Equation 1,

$$(N - 1)D(N - 1) = 2 \sum_{j=0}^{N-2} D(j) + c(N - 1)^2 \quad \text{--- Equation 2.}$$

Subtracting Equation 2 from Equation 1,

$$ND(N) = (N + 1)D(N - 1) + 2cN \quad \text{--- Equation 3}$$

Continued

Dividing both sides of Equation 3 by $N(N - 1)$

$$\frac{D(N)}{N+1} = \frac{D(N-1)}{N} + \frac{2c}{N+1}$$

$$\frac{D(N-1)}{N} = \frac{D(N-2)}{N-1} + \frac{2c}{N}$$

.....

.....

$$\frac{D(2)}{3} = \frac{D(1)}{2} + \frac{2c}{3}$$

Continued

Adding all the equations in the previous slide,

$$\frac{D(N)}{N+1} = \frac{D(1)}{2} + 2c \sum_{i=3}^{N+1} \frac{1}{i}$$

$$D(N) = 2c(N+1) \sum_{i=3}^{N+1} \frac{1}{i}$$

$$D(N) = 2c(N+1)O(\lg N)$$

$$D(N) = O(N \lg N)$$

$$\text{Average height} = \frac{O(N \lg N)}{N} = O(\lg N)$$

Performance of BST methods

- What is the asymptotic performance of each of the BST methods?

	Best Case	Worst Case	Average Case
contains			
insert			
remove			
findMin/ Max			
makeEmpty			
assignment			

Predecessor in BST

- Predecessor of a node v in a BST is the node that holds the data value that immediately precedes the data at v in order.
- Finding predecessor
 - v has a left subtree
 - then predecessor must be the largest value in the left subtree (the rightmost node in the left subtree)
 - v does not have a left subtree
 - predecessor is the first node on path back to root that does not have v in its left subtree

Successor in BST

- Successor of a node v in a BST is the node that holds the data value that immediately follows the data at v in order.
- Finding Successor
 - v has right subtree
 - successor is smallest value in right subtree
(the leftmost node in the right subtree)
 - v does not have right subtree
 - successor is first node on path back to root that does not have v in its right subtree

Building a BST

- Given an array/vector of elements, what is the performance (best/worst/average) of building a BST from scratch?

Tree Iterators

- As we know there are several ways to traverse through a BST. For the user to do so, we must supply different kind of iterators. The iterator type defines how the elements are traversed.
 - InOrderIterator<T> **inOrderIterator()** ;
 - PreOrderIterator<T> **preOrderIterator()** ;
 - PostOrderIterator<T> **postOrderIterator()** ;
 - LevelOrderIterator<T> **levelOrderIterator()** ;

Using Tree Iterator

```
public static void main (String args[ ] )
{
    BinarySearchTree<Integer> tree = new
                                BinarySearchTree<Integer>();

    // store some ints into the tree

    InOrderIterator<Integer> itr =
                                tree.inOrderIterator( );
    while ( itr.hasNext( ) )
    {
        Object x = itr.next();
        // do something with x
    }
}
```

The InOrderIterator is a Disguised List Iterator

```
// An InOrderIterator that uses a list to store
// the complete in-order traversal
import java.util.*;
class InOrderIterator<T>
{
    Iterator<T> _listIter;
    List<T> _theList;

    T next()
    {   /*TBD*/ }

    boolean hasNext()
    {   /*TBD*/ }

    InOrderIterator(BinarySearchTree.BinaryNode<T> root)
    {   /*TBD*/ }

}
```

List-Based InOrderIterator Methods

```
//constructor
InOrderIterator( BinarySearchTree.BinaryNode<T> root )
{
    fillListInorder( _theList, root );
    _listIter = _theList.iterator( );
}

// constructor helper function
void fillListInorder (List<T> list,
                     BinarySearchTree.BinaryNode<T> node)
{
    if (node == null) return;
    fillListInorder( list, node.left );
    list.add( node.element );
    fillListInorder( list, node.right );
}
```

List-based InOrderIterator Methods

Call List Iterator Methods

```
T next( )  
{  
    return _listIter.next( );  
}
```

```
boolean hasNext( )  
{  
    return _listIter.hasNext( );  
}
```

InOrderIterator Class with a Stack

```
// An InOrderIterator that uses a stack to mimic recursive traversal
class InOrderIterator
{
    Stack<BinarySearchTree.BinaryNode<T>> _theStack;

    //constructor
    InOrderIterator(BinarySearchTree.BinaryNode<T> root) {
        _theStack = new Stack();
        fillStack( root );
    }

    // constructor helper function
    void fillStack(BinarySearchTree.BinaryNode<T> node) {
        while(node != null){
            _theStack.push(node);
            node = node.left;
        }
    }
}
```

Stack-Based InOrderIterator

```
T next( ) {
    BinarySearchTree.BinaryNode<T> topNode = null;
    try {
        topNode = _theStack.pop();
    } catch (EmptyStackException e)
    {
        return null;
    }
    if (topNode.right != null){
        fillStack(topNode.right);
    }
    return topNode.element;
}

boolean hasNext( ) {
    return !_theStack.empty();
}
```

More Recursive BST Methods

- `bool isBST (BinaryNode<T> t)`
returns true if the Binary tree is a BST
- `const T& findMin(BinaryNode<T> t)`
returns the minimum value in a BST
- `int countFullNodes (BinaryNode<T> t)`
returns the number of full nodes (those with 2 children) in a binary tree
- `int countLeaves(BinaryNode<T> t)`
counts the number of leaves in a Binary Tree