CMSC 341

K-D Trees

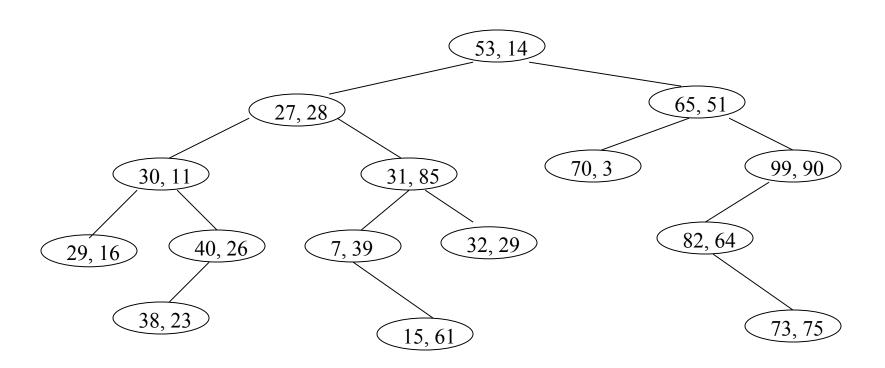
K-D Tree

- Introduction
 - Multiple dimensional data
 - Range queries in databases of multiple keys:
 - Ex. find persons with
 - $34 \le age \le 49$ and $$100k \le annual\ income \le $150k$
 - GIS (geographic information system)
 - Computer graphics
 - Extending BST from one dimensional to k-dimensional
 - It is a binary tree
 - Organized by levels (root is at level 0, its children level 1, etc.)
 - Tree branching at level 0 according to the first key, at level 1 according to the second key, etc.

KdNode

 Each node has a vector of keys, in addition to the two pointers to its left and right subtrees.

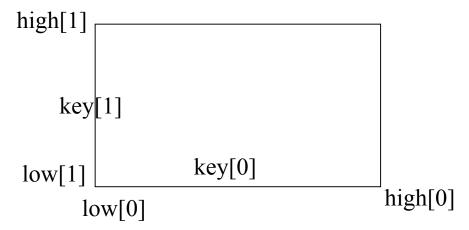
K-D Tree



A 2-D tree example

K-D Tree Operations

- Insert
 - A 2-D item (vector of size 2 for the two keys) is inserted
 - New node is inserted as a leaf
 - Different keys are compared at different levels
- Find/print with an orthogonal (square) range

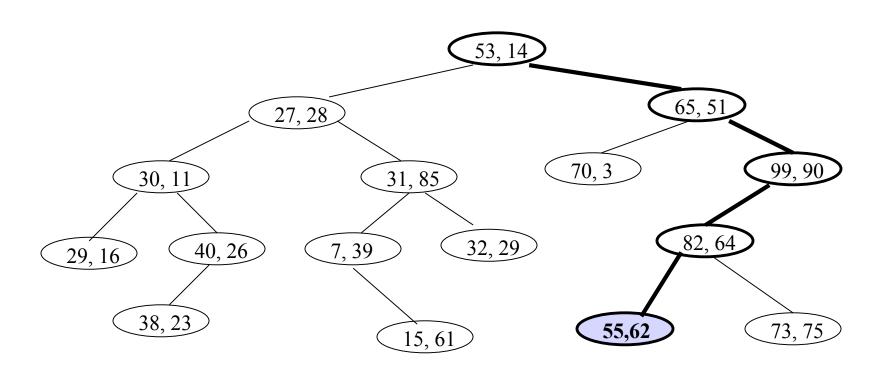


- exact match: insert (low[level] = high[level] for all levels)
- partial match: (query ranges are given to only some of the k keys, other keys can be thought in range ± ∞)

K-D Tree Insertion

```
template <class Comparable>
void KdTree <Comparable>::insert(const vector<Comparable> &x)
   insert( x, root, 0);
template <class Comparable>
void KdTree <Comparable>::
insert(const vector<Comparable> &x, KdNode * & t, int level)
   if (t == NULL)
      t = new KdNode(x);
   else if (x[level] < t->data[level])
      insert(x, t\rightarrowleft, 1 - level);
   else
      insert(x, t->right, 1 - level);
```

Insert (55, 62) into the following 2-D tree



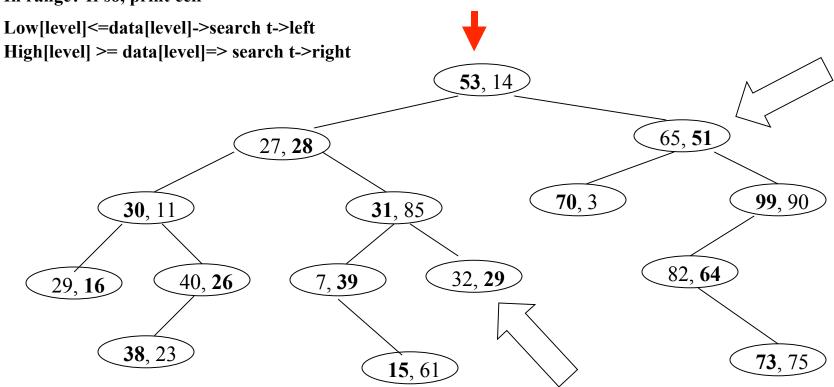
K-D Tree: printRange

K-D Tree: printRange (cont'd)

```
template <class Comparable>
void KdTree <Comparable>::
printRange(const vector<Comparable> &low,
           const vector < Comparable > & high,
          KdNode * t, int level)
   if (t != NULL)
     if (low[0] \le t->data[0] \&\& high[0] >= t->data[0]
     && low[1] \le t-data[1] && high[1] >= t-data[1])
        cout << "(" << t->data[0] ","
              << t->data[1] << ")" << endl;
     if (low[level] <= t->data[level])
        printRange(low, high, t->left, 1 - level);
     if (high[level] >= t->data[level])
        printRange(low, high, t->right, 1 - level);
```

printRange in a 2-D Tree

In range? If so, print cell



$$low[0] = 35, high[0] = 40;$$

 $low[1] = 23, high[1] = 30;$

This subtree is never searched

Searching is "preorder". Efficiency is obtained by "pruning" subtrees from the search.

K-D Tree Performance

- Insert
 - Average and balanced trees: O(lg N)
 - Worst case: O(N)
- Print/search with a square range query
 - Exact match: same as insert (low[level] = high[level] for all levels)
 - Range query: for M matches
 - Perfectly balanced tree:

K-D trees: $O(M + kN^{(1-1/k)})$

2-D trees: $O(M + \sqrt{N})$

• Partial match

in a random tree: O(M + N $^{\alpha}$) where $\alpha = (-3 + \sqrt{17}) / 2$

K-D Tree Performance

- More on range query in a perfectly balanced 2-D tree:
 - Consider one boundary of the square (say, low[0])
 - Let T(N) be the number of nodes to be looked at with respect to low[0]. For the current node, we may need to look at
 - One of the two children (e.g., node (27, 28), and
 - Two of the four grand children (e.g., nodes (30, 11) and (31, 85).
 - Write T(N) = 2 T(N/4) + c, where N/4 is the size of subtrees 2 levels down (we are dealing with a perfectly balanced tree here), and c = 3.
 - Solving this recurrence equation:

$$T(N) = 2T(N/4) + c = 2(2T(N/16) + c) + c$$
...
$$= c(1 + 2 + \dots + 2^{(\log_4 N)}) = 2^{(1 + \log_4 N)} - 1$$

$$= 2*2^{(\log_4 N)} - 1 = 2^{(\log_2 N)/2} - 1 = O(\sqrt{N})$$

K-D Tree Remarks

- Remove
 - No good remove algorithm beyond lazy deletion (mark the node as removed)
- Balancing K-D Tree
 - No known strategy to guarantee a balanced 2-D tree
 - Tree rotation does not work here
 - Periodic re-balance
- Extending 2-D tree algorithms to k-D
 - Cycle through the keys at each level