

DIFFUSION MODELS

- DM is a generative model

↳ RECALL (other) Gen. Models
VAE, GAN, ...

- Problem Formulation (Basic case)

Training Set : $\{x^{(1)}, \dots, x^{(N)}\} \sim q_{\text{data}}(x)$

↳ N images with an unknown underlying distribution q

GOAL : learn generative model $p_{\theta}(x)$

s.t. $p_{\theta}(x) \sim q_{\text{data}}(x)$

i.e. learn a parametric model to approximate the unknown underlying distribution q

+ we want easy sampling from p

(want to generate new images)

* Compared to VAE / GAN, DM uses a different approach for $x = G(z)$

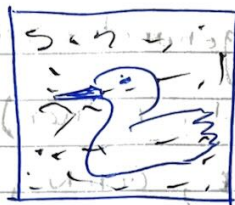
KEY IDEA

add & remove noise from images
learn p_{θ} from this add / remove process

clean
training / original image
(known)



add noise



add noise



$\sim q_{\text{data}}$
(unknown)

as you add
more noise

totally
noisy

$q(x_0)$

original noiseless
distribution

$q(x_1)$

$q(x_T)$

FORWARD PROCESS

"noising"

$q(x_0)$: original distribution

$q(x_T)$: noise distribution (after T steps, of

at each step of FWD process, we add "noising" small amount of noise

Q: do we know the noise distribution?

Q: if we have a good noise model, can we characterize $q(x_t)$ in terms of $q(x_0)$?

$$q(x_t | x_{t-1}) \sim N(\sqrt{1-\beta_t} x_{t-1}, \beta_t I)$$

if noise is Gaussian,

mean is func. of previous sample
(scaled by $\sqrt{1-\beta_t}$)

var is β_t times Identity

Mean

variance

in other words:

$$X_t = \sqrt{1-\beta_t} X_{t-1} + \sqrt{\beta_t} \varepsilon$$

$\beta_t = \text{coeff}$

$$\varepsilon \sim \mathcal{N}(0, I)$$

why?

ensures that variance is preserved (doesn't explode)

Q: do we need to sequentially generate X_t ?
or can we write X_T directly?

↳ it's not deterministic because ε is sampled from $\mathcal{N}(0, I)$
(it's not the same everytime)

$$X_1 = \sqrt{1-\beta_1} X_0 + \sqrt{\beta_1} \varepsilon_0$$

$$X_2 = \sqrt{1-\beta_2} X_1 + \sqrt{\beta_2} \varepsilon_1$$

$$= \underbrace{\sqrt{1-\beta_2}}_{\alpha_2} \underbrace{\sqrt{1-\beta_1}}_{\alpha_1} X_0 + \underbrace{\sqrt{1-\beta_2} \sqrt{\beta_1} \varepsilon_0 + \sqrt{\beta_2} \varepsilon_1}_{\text{Gaussian } N(0, (1-\alpha_2)I)}$$

define: $1-\beta_2 = \alpha_2$, $1-\beta_1 = \alpha_1$,

combined $\frac{1}{\alpha_2} = \alpha_1, \alpha_2 = (1-\beta_1)(1-\beta_2)$

$$\bar{\alpha}_t = \alpha_1 \dots \alpha_t = \prod_{i=1}^t (1-\beta_i)$$

$$\therefore X_2 = \sqrt{\bar{\alpha}_2} X_0 + \sqrt{1-\bar{\alpha}_2} \varepsilon \quad \varepsilon \sim \mathcal{N}(0, I)$$

in general $X_t = \sqrt{\bar{\alpha}_t} X_0 + \sqrt{1-\bar{\alpha}_t} \varepsilon$

"FORWARD PROCESS"

$$X_t = \sqrt{\alpha_t} X_0 + \sqrt{1 - \alpha_t} \varepsilon, \quad \varepsilon \sim N(0, I)$$

$$\alpha_t = \alpha_1 \alpha_2 \dots \alpha_t = (1 - \beta_1) \dots (1 - \beta_t)$$

note: ~~note~~ $\beta_t \in (0, 1) \Rightarrow \alpha_t \in (0, 1) \forall t$

example: assume each $\beta = 1/2$

$$\text{after } T = 1000, \quad \sqrt{\alpha_t} = \left(\left(\frac{1}{2} \right)^{1000} \right)^{1/2}$$

$$X_{1000} = \underbrace{\left(\frac{1}{2} \right)^{500}}_{\sim 0} X_0 + \underbrace{\sqrt{1 - \left(\frac{1}{2} \right)^{500}}}_{\sim 1} \varepsilon$$

$$X_{1000} \sim \varepsilon$$

(after a lot of steps, $X_{1000} \rightarrow \text{noise}$)

$$\cancel{X_t \sim N(0, I)} \text{ as } T \rightarrow \infty$$

$$q(X_T | X_0) \rightarrow N(0, I)$$

or

$$\lim_{T \rightarrow \infty} q(X_T | X_0) = N(0, I)$$

REVERSE BACKWARD PROCESS?

Can we generate q_{t-1} from q_t ?

(Can we do "denoising"?)

↳ for now, let's assume we can

if we can,

does it help us get $p_\theta(x)$?

↓

YES!

we can start from noise $\mathcal{E} = x_T$

(and start iterative "denoising")

to obtain CLEANER $\hat{x}_{T-1}, \hat{x}_{T-2}, \dots$

all the way to $\hat{x}_0$

and

$\hat{x}_0 \sim q_0$

↓

distribution of original data

$q_{1000} \rightarrow q_{999} \rightarrow q_{998} \dots \rightarrow q_1 \rightarrow q_0$

GOAL: $q(x_{t-1} | x_t)$

Can we simplify conditional distributions?

BAYES!

$$q(x_{t-1} | x_t) = \frac{\text{GAUSSIAN! } q(x_t | x_{t-1}) q(x_{t-1})}{q(x_t)}$$

but do we know $q(x_{t-1})$ and $q(x_t)$

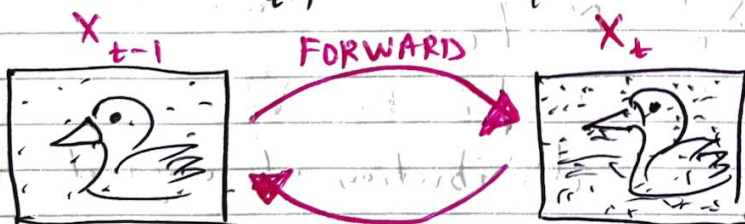
↳ not in general, but we know

that for high t , $q(x_t) \sim \mathcal{E}$

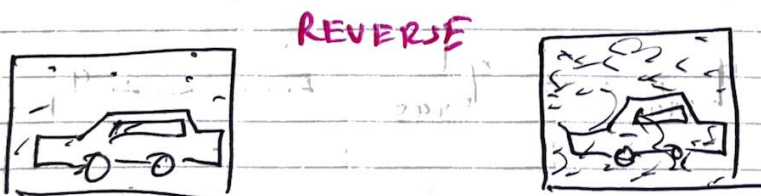
but we don't have $q(x_{t-1})$

... WHAT CAN WE DO?

— consider x_{t-1} that you obtain from FWD process



$$q(x_{t-1} | x_t) = ?$$



"DENOISING"



Recall VAE:

decoder

$$z \sim \mathcal{N}(\mu, \sigma^2) \quad \mathcal{G}(z) = \hat{x}$$

$E(x)$

We can model $q(x_{t-1} | x_t)$

using a parametric model

$$P_{\theta}(x_{t-1} | x_t)$$

neural network model with weights θ
we will learn θ

P_{θ} will progressively denoise from $x_T = \text{noise}$

P_{θ} is the generator

gradually add noise $t-1 \rightarrow t$

find parameters θ that can reverse this.

@ each step

Ok we need to model $P_{\theta}(x_{t-1} | x_t)$

let's model P_θ with a Gaussian
(Gaussians are simple)

$$P_\theta(X_{t-1} | X_t) = N(\text{mean}, \text{var})$$

mean: modeled by NN

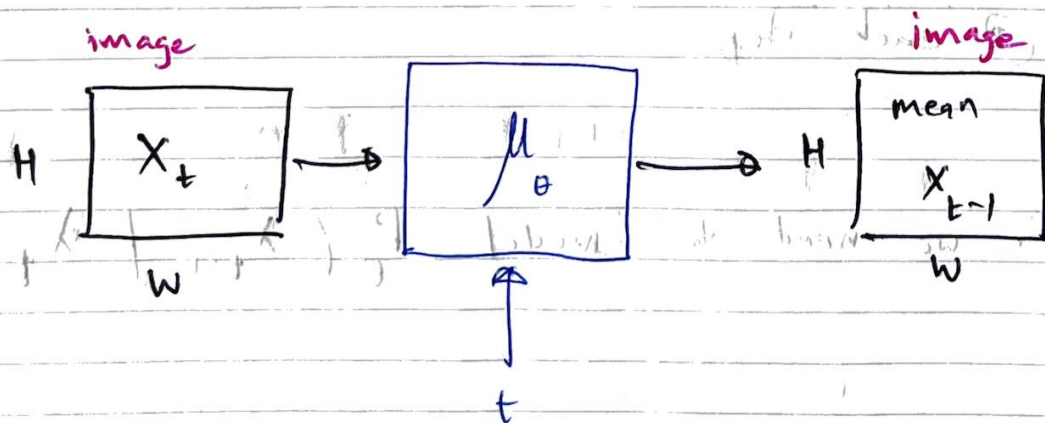
$$\mu_\theta(X_t, t)$$

var: some noise

$$\sigma_t^2 I$$

$$P_\theta(X_{t-1} | X_t) = N(\mu_\theta(X_t, t), \sigma_t^2 I)$$

does this have to be a function of time?
not necessarily, but often helpful



Now, given this model, we get a generative process

we can express $P_\theta(x_0)$ now x_0 : clean image

$$P_\theta(x_0) = P(x_T) P_\theta(x_{T-1} | x_T) \dots P_\theta(x_0 | x_1)$$

$\sim N(0, I)$

That's it!

SOTA models for image generation, video generation, audio generation

One missing piece: how to learn θ ?

$\mu_\theta(x_t, t)$ just do MLE ...

$$\max_{\theta} \mathbb{E}_{x_0 \sim q(x_0)} [\log P_\theta(x_0)] \iff \theta^*$$

(real data)

can we solve this directly? No.

↳ we need to use variational lower bound (ELBO)

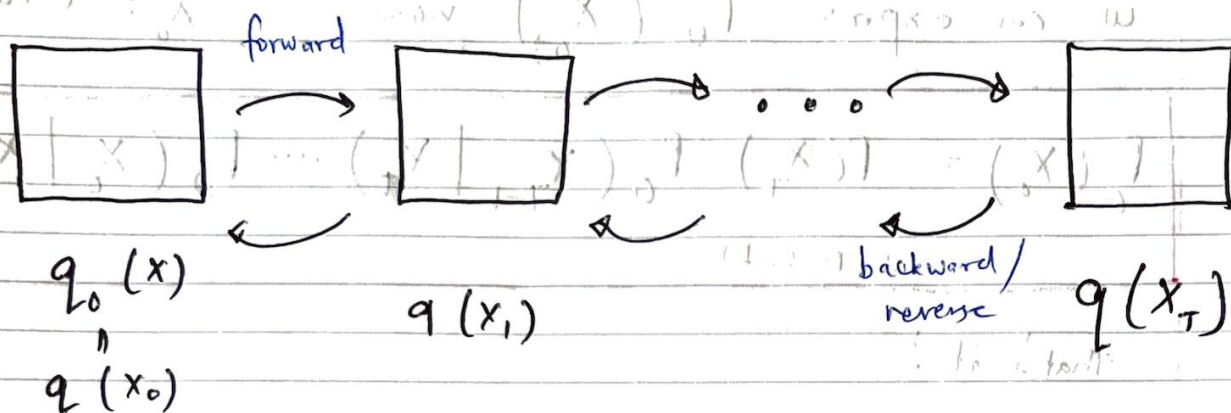
Read:

Sohl-Dickstein 2015

Ho et al. 2020

we will not discuss in class

RECAP / SUMMARY of DIFFUSION MODELING



Forward: start with clean image distribution $q(x_0)$
add noise progressively to get $q(x_1) \dots q(x_T)$

Reverse: start with $p(x_T) \sim N(0, I)$

model with $(\text{NN } \theta)$ $p_\theta(x_{t-1} | x_t) \sim N(\underbrace{\mu_\theta(x_t, t)}_{\sigma_t^2 I})$

$$\log p_\theta(x) \geq \mathbb{E}_{q(x_{1:T} | x_0)} \left[\log \frac{p_\theta(x_{0:T})}{q(x_{1:T} | x_0)} \right] \quad \text{ELBO}$$

$$\theta^* = \min_{\theta} (-\text{ELBO})$$