

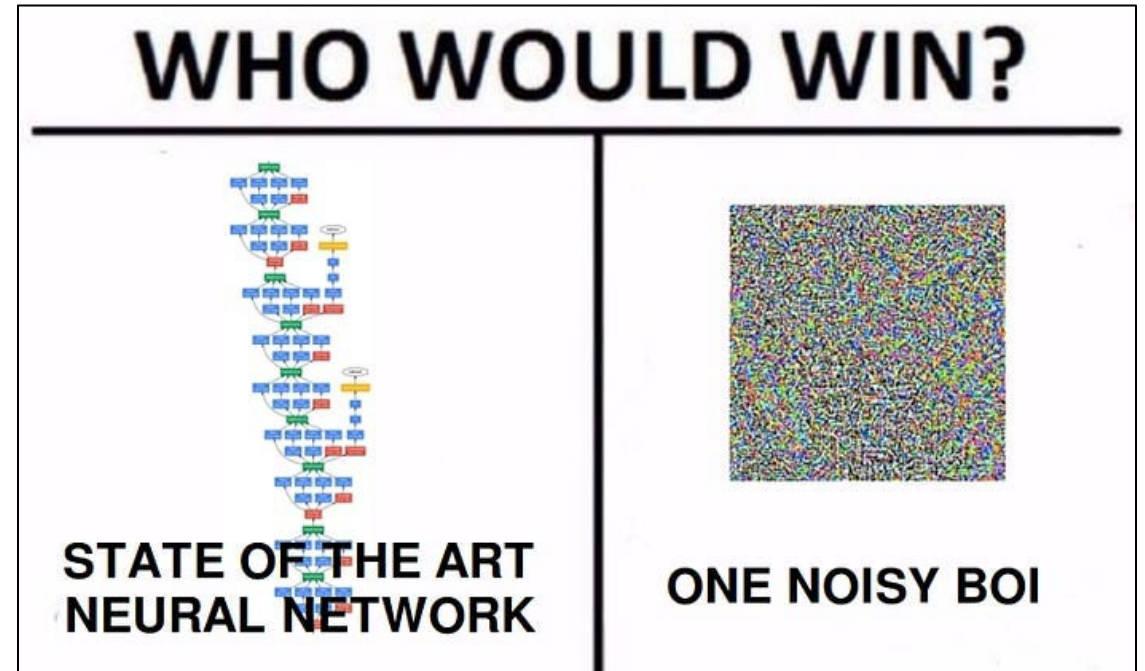
Midterm Exam Feedback

Email your answers to gokhale@umbc.edu with subject "[Neural Networks] Midterm Feedback".
Everyone who completes this feedback by April 6 will receive +2 extra credit.

1. Did you attend the lecture on 03/26 where we did a "midterm review" ?
2. Did you have enough time to complete all questions ?
 - If no, how much more time would have been enough ?
3. Which part (1/2/3/4) was the hardest ? Why ?
4. Which part (1/2/3/4) was the easiest ? Why ?
5. **[current/past UMBC undergrads]** Have CSEE classes (100 to 300 level) prepared you for 475/675 or other "AI" classes (471/472/473/478/...)?
 - If yes, which ones ?
 - If no, which topics do you wish we taught you before you took 475/675 ?

Lecture 10

Adversarial Robustness



Chihuahua ... or Muffin ... ?



Chihuahua ... or Muffin ... ?



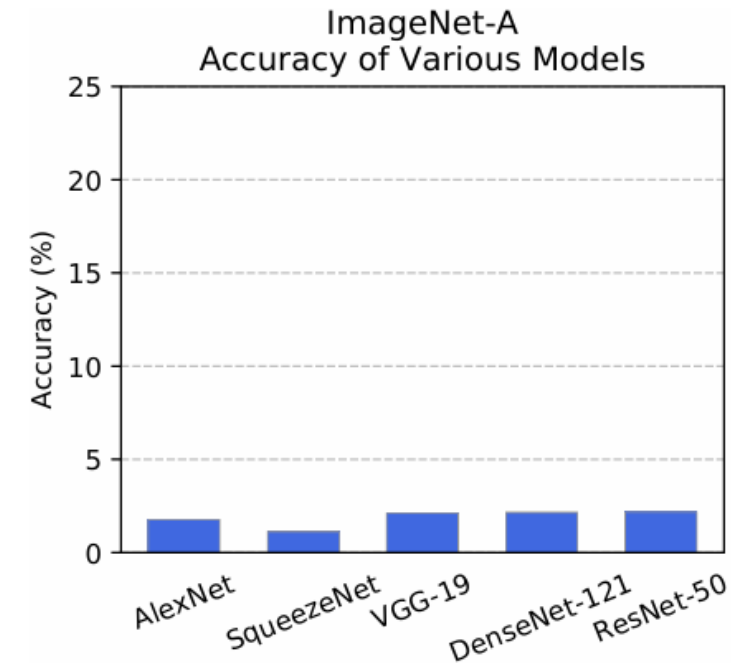
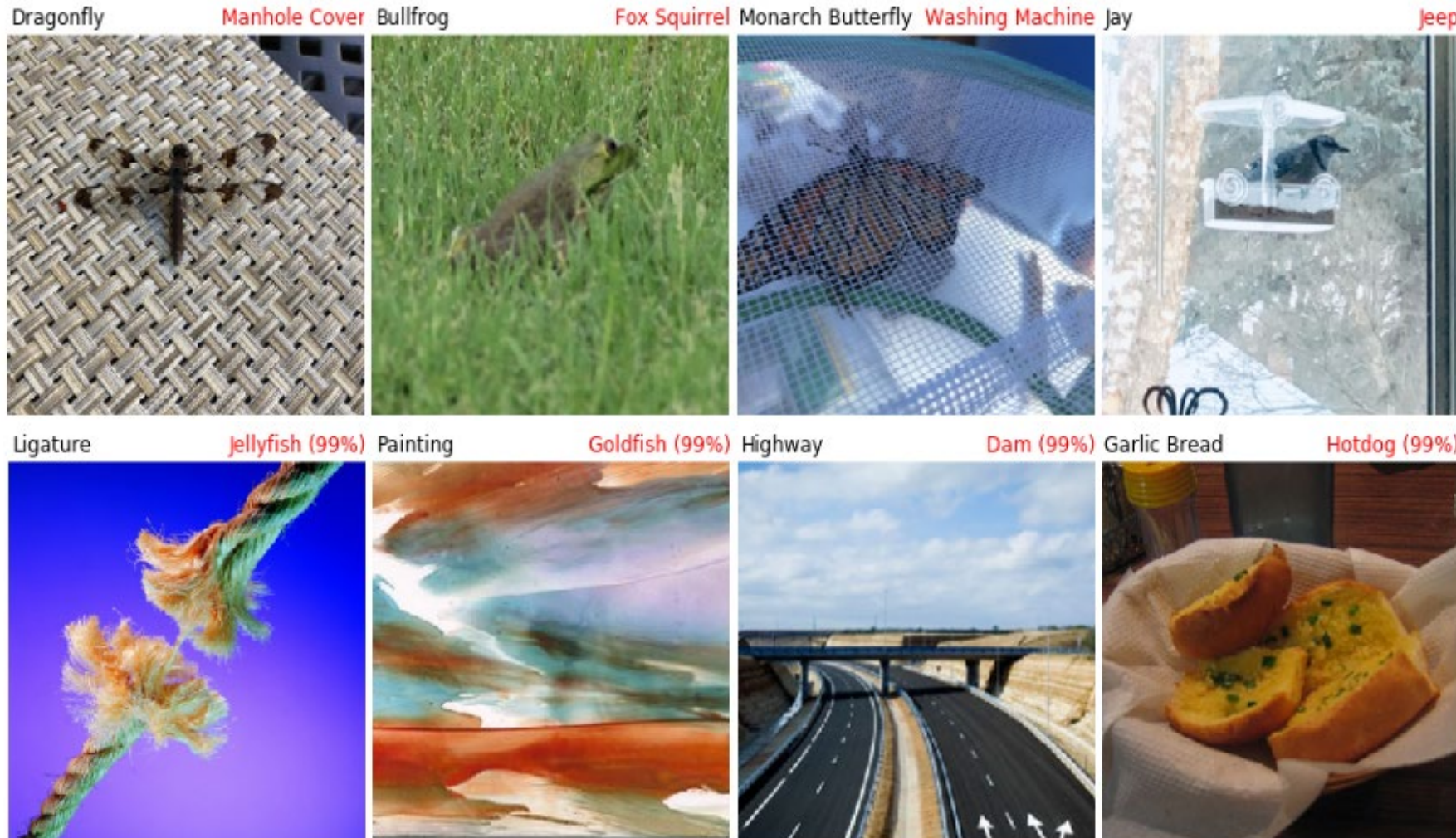
**Mop ...
or Sheepdog ... ?**



NNs get fooled ... *very easily* ...



*"manually constructed by
graduate students
over several months"*



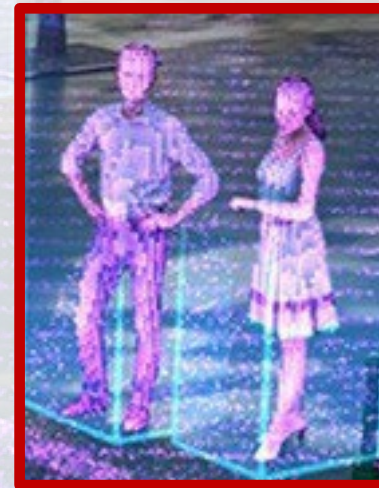
Biker



Pedestrian Sign



Persons



Bike
r



+ .007



=



Small but carefully-crafted
adversarial perturbation

Green Traffic
Light

Adversarial
Perturbation Attack

Pedestrian Sign



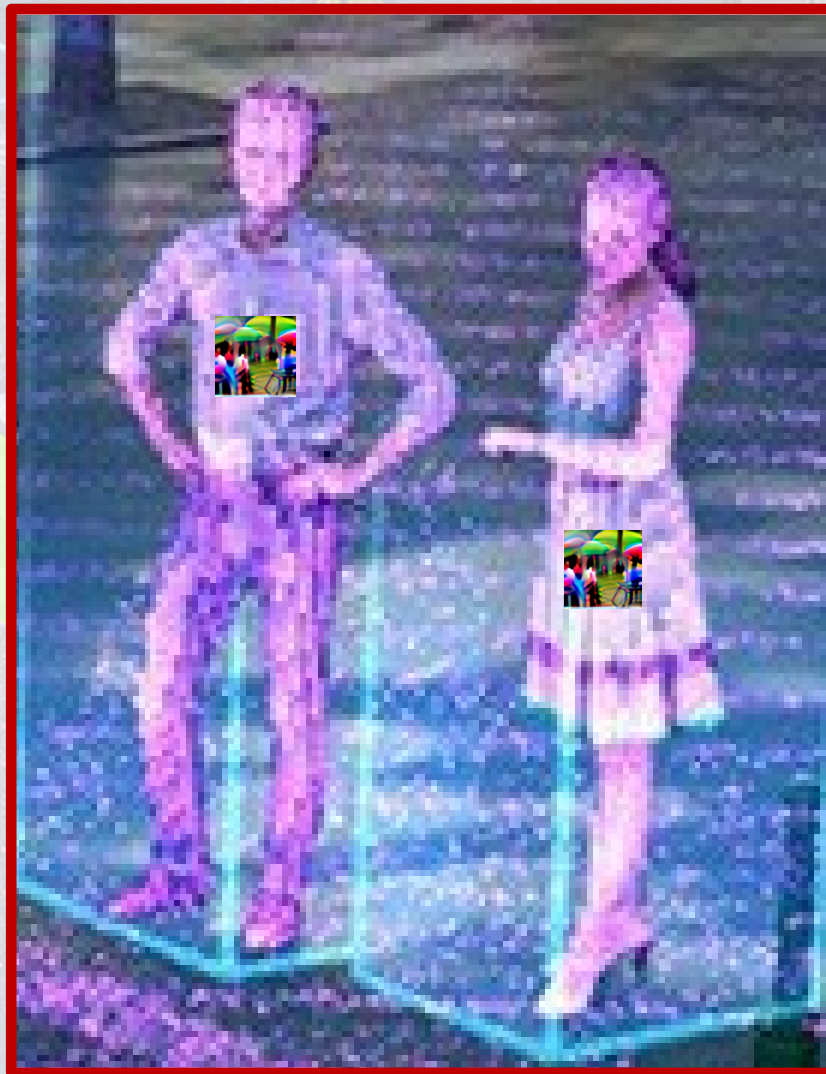
**Speed Limit 45
Sign**

**Adversarial
Rotation Attack**

No Person

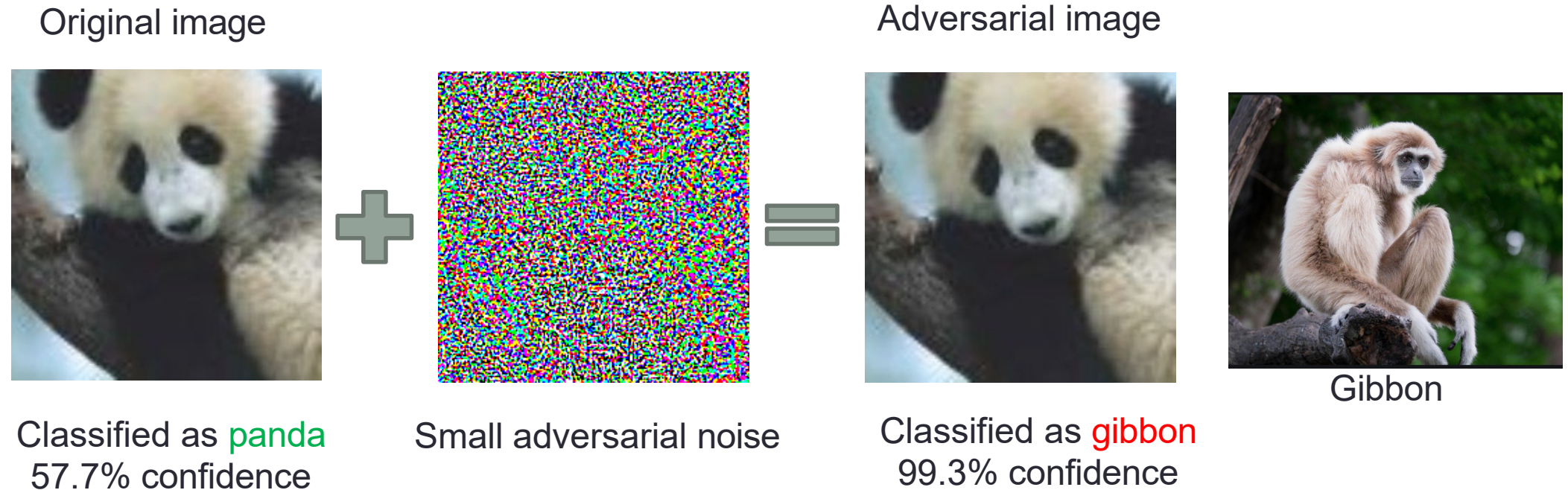
Persons

**Adversarial
Patch Attack**



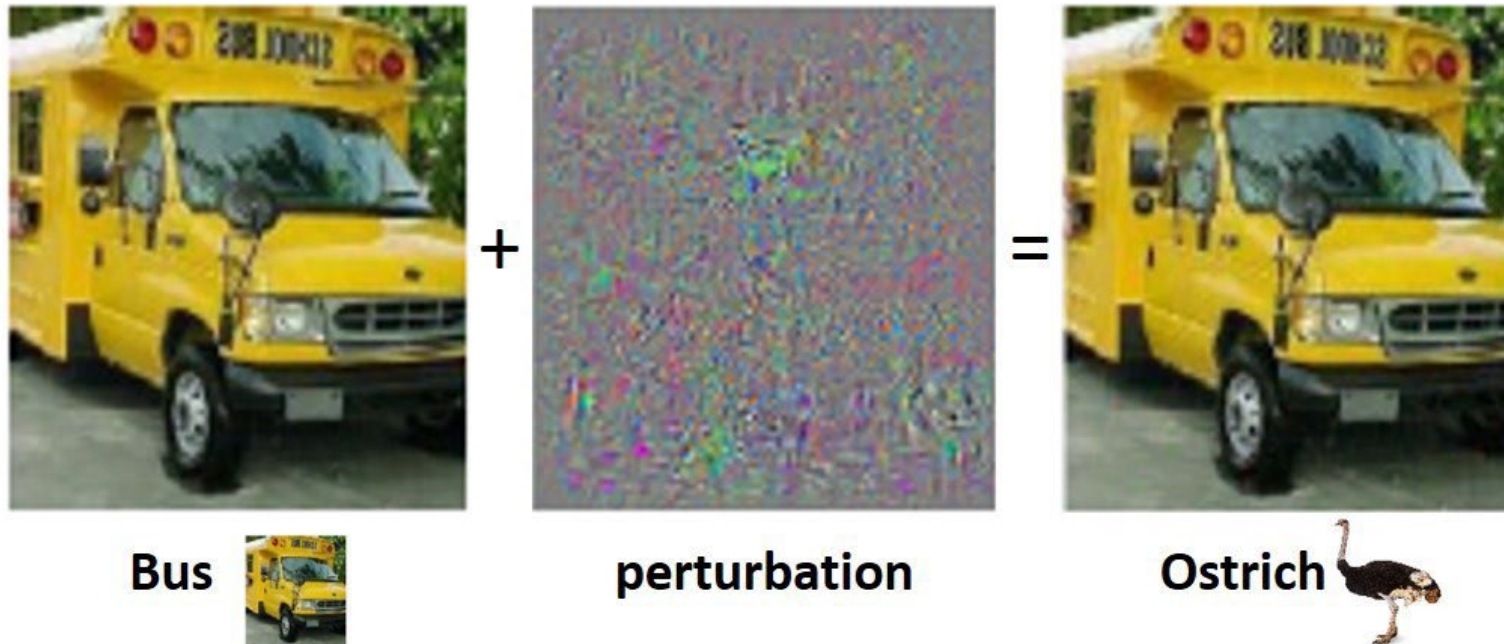
Adversarial Examples

- In 2014, one of the seminal papers of Goodfellow et al. shows that an adversarial image of a panda can fool the ML model to output “gibbon”
- This paper was influential in building community interest in “adversarial ML”



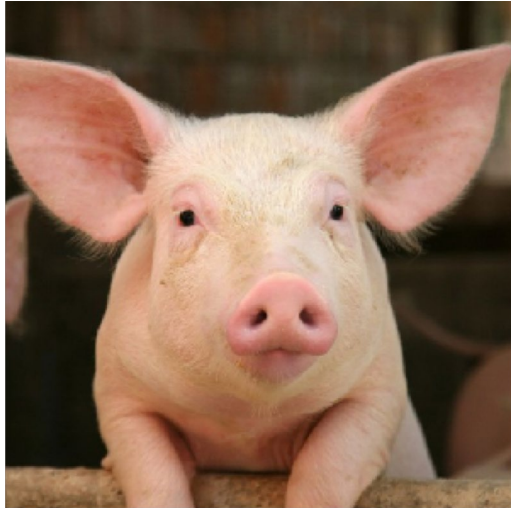
Adversarial Examples

- Similar example, from Szegedy et al. (2014)



ML Predictions Are (Mostly) Accurate but Brittle

“pig” (91%)



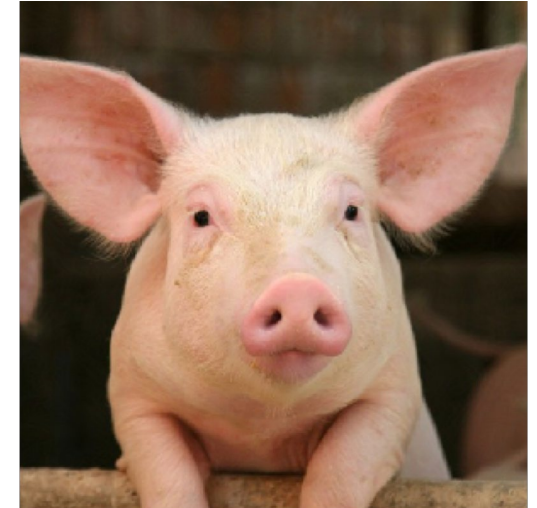
+ 0.005 x

noise (NOT random)



=

“airliner” (99%)



[Szegedy Zaremba Sutskever Bruna Erhan Goodfellow Fergus 2013]

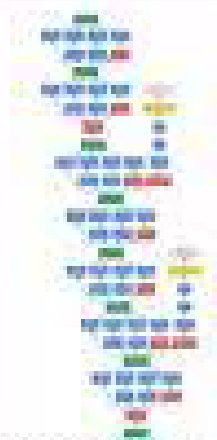
[Biggio Corona Maiorca Nelson Srndic Laskov Giacinto Roli 2013]

But also: [Dalvi Domingos Mausam Sanghai Verma 2004][Lowd Meek 2005]

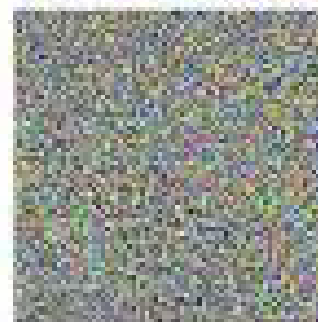
[Globerson Roweis 2006][Kolcz Teo 2009][Barreno Nelson Rubinstein Joseph Tygar 2010]

[Biggio Fumera Roli 2010][Biggio Fumera Roli 2014][Srndic Laskov 2013]

WHO WOULD WIN?



STATE OF THE ART
NEURAL NETWORK

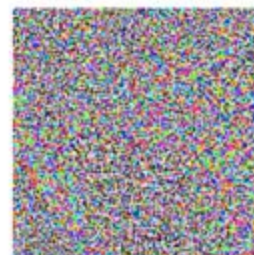


ONE NOISY BOI



x
“panda”
57.7% confidence

$+ .007 \times$



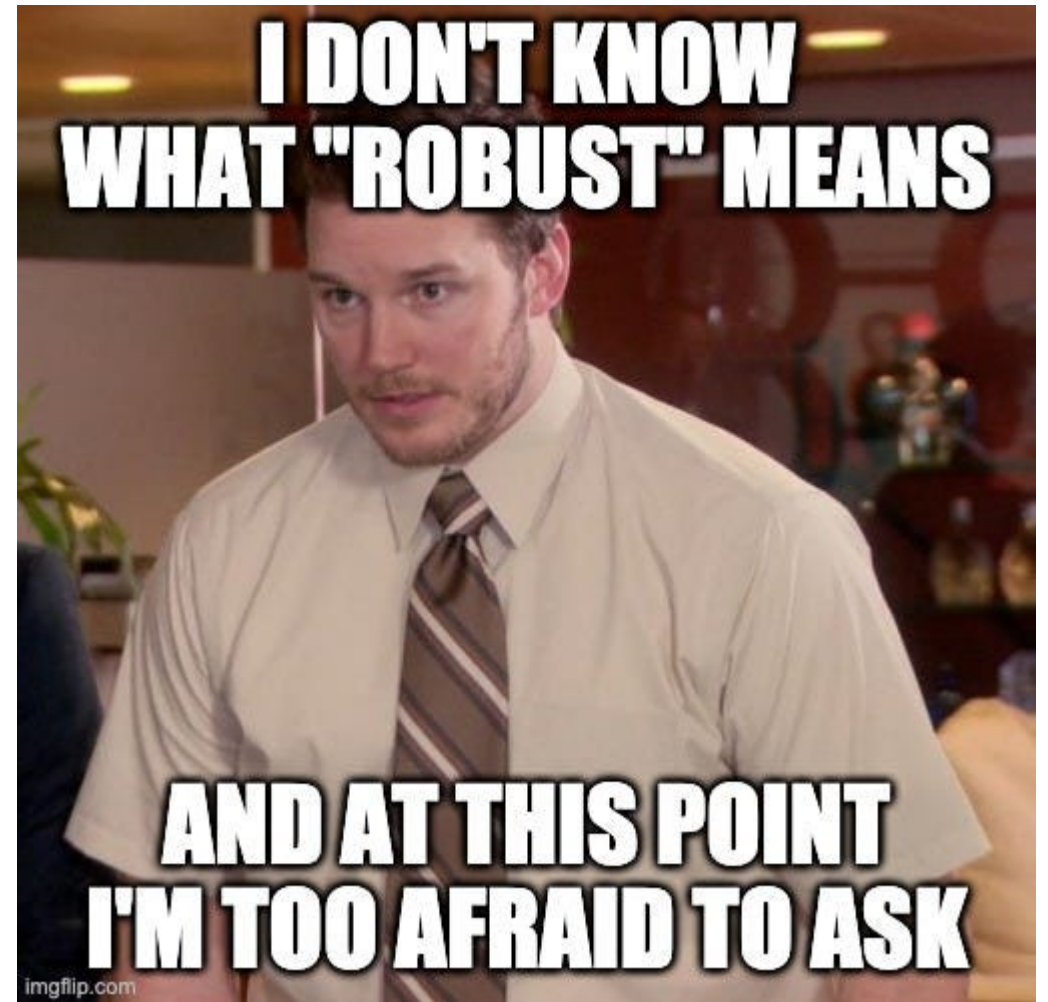
$\text{sign}(\nabla_x J(\theta, x, y))$
“nematode”
8.2% confidence

$=$



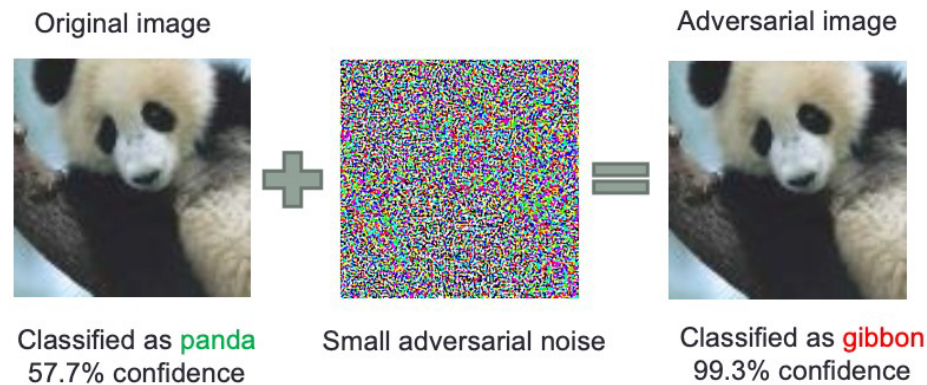
$x + \epsilon \text{sign}(\nabla_x J(\theta, x, y))$
“gibbon”
99.3 % confidence

Robustness Definitions (or the lack thereof)

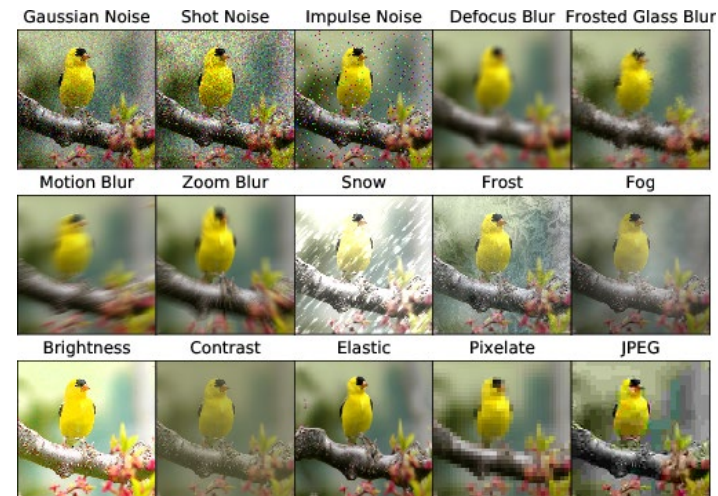


Adversarial vs. Out-of-distribution

- Each of the described attacks can further be:
 - Adversarial** example (algorithmically manipulated example)

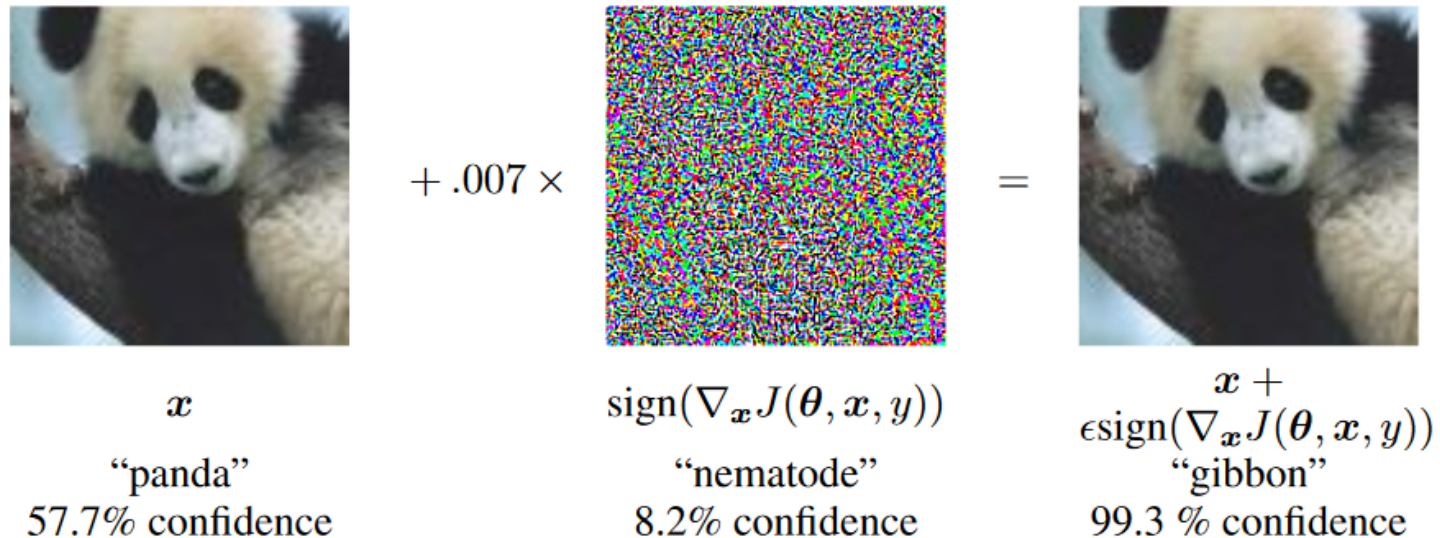


- Out-of-distribution** example (natural example)



Adversarial “Attacks”

- Algorithms that can “find” perturbations to add to images, in order to fool classifiers
- Given image x , find $g(x)$ s.t. $x + \epsilon g(x)$ fools classifier
- Perturbations are typically norm-bounded

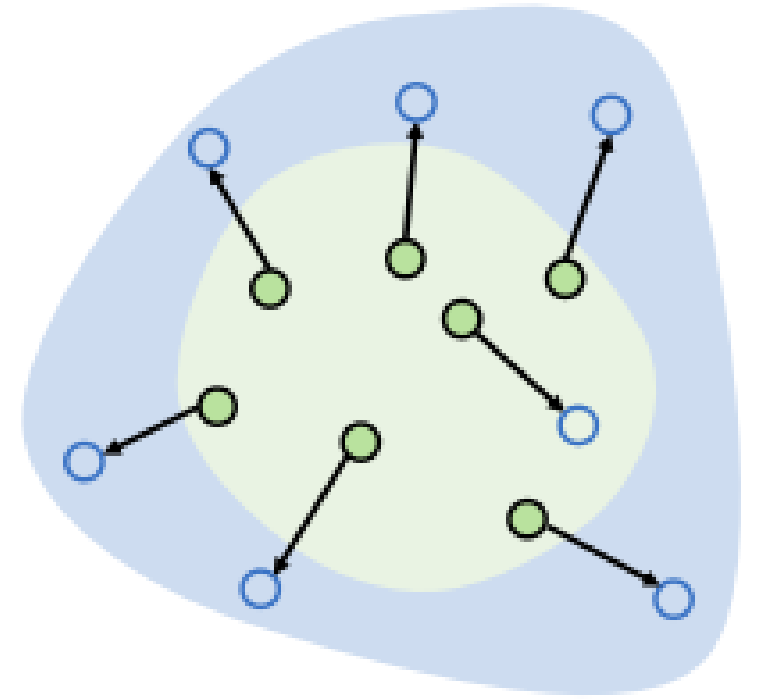


A web demo to create your own adversarial examples

<https://kennysong.github.io/adversarial.js/>

Adversarial “Defense”

- Algorithms that make the model robust against attacks
- Leverages the concept of adversarial examples, to improve classifier robustness to such attacks
- min—max optimization
 - *maximization*: find adversarial images
 - *minimization*: train classifier to correctly classify such images
- norm-bounded perturbations: robustness within the norm-ball



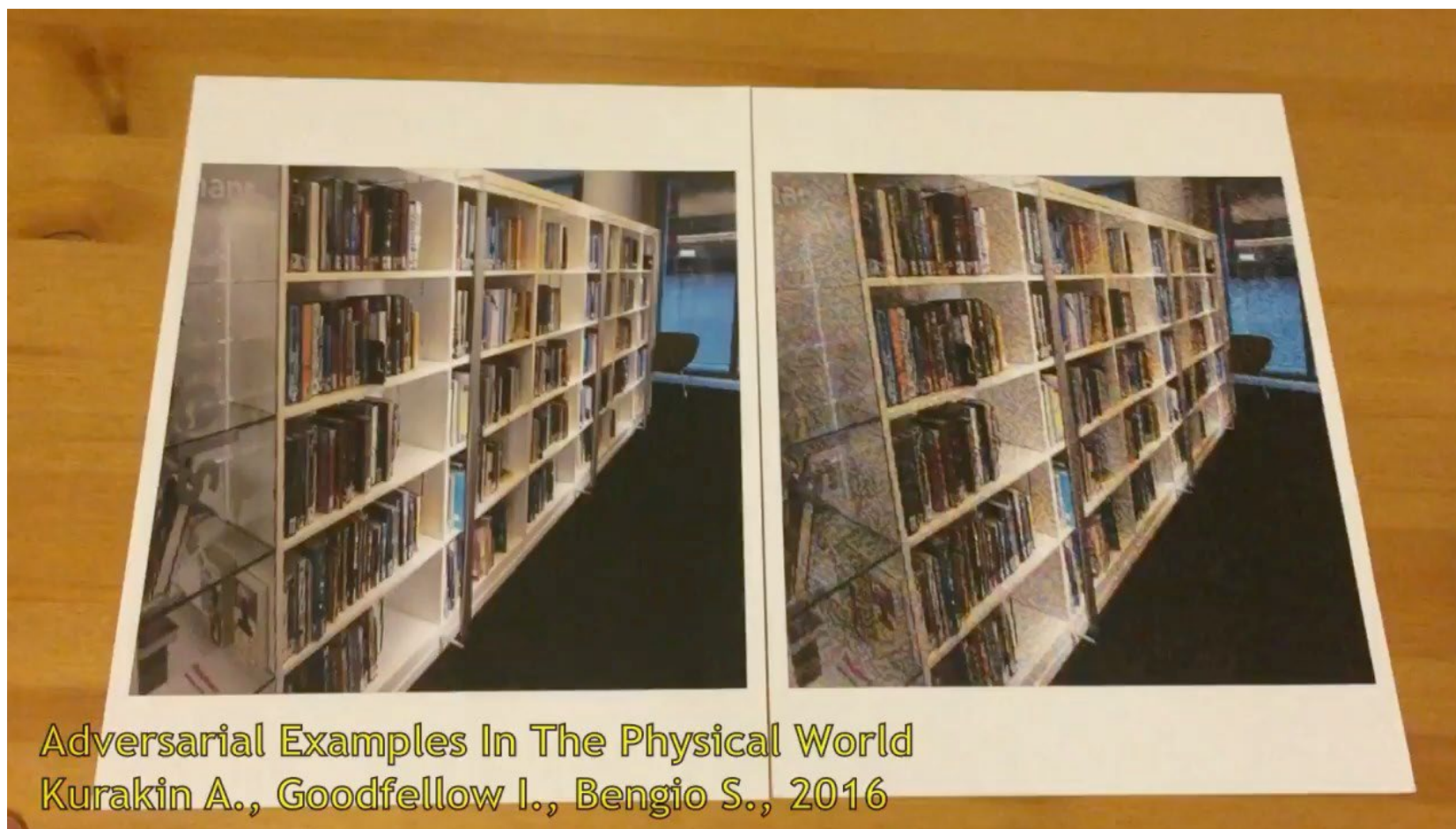
$$\min_{\theta} \rho(\theta), \quad \text{where} \quad \rho(\theta) = \mathbb{E}_{(x,y) \sim \mathcal{D}} \left[\max_{\delta \in \mathcal{S}} L(\theta, x + \delta, y) \right]$$

We will look at adversarial attack-defense
as a mathematical formalism soon ...

First, let's see some examples of
other types of “adversarial attacks”

Physical-World Attack: Printed Adversarial Images

- Not only adversarial examples in the **digital** world, but **printed** adversarial images can also fool machine learning models

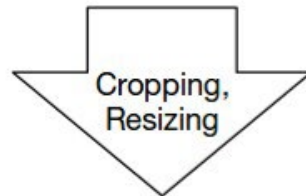


Physical-World Attack: Adversarial STOP Sign

- An example of manipulating a STOP sign with adversarial patches
 - **Methodology:** carefully design a patch and attach it to the STOP sign
 - Cause the DL model of a self-driving car to misclassify it as a Speed Limit 45 sign
 - The authors achieved 100% attack success in lab test, and 85% in field test

Lab (Stationary) Test

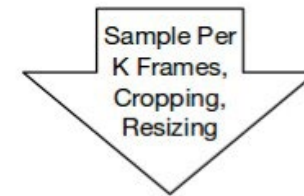
Physical road signs with adversarial perturbation under different conditions



Stop Sign → Speed Limit Sign

Field (Drive-By) Test

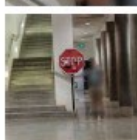
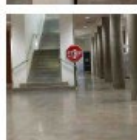
Video sequences taken under different driving speeds



Stop Sign → Speed Limit Sign

Physical-World Attack: Adversarial STOP Sign

- More examples of lab test for STOP signs with a target class Speed Limit 45

Distance/Angle	Subtle Poster	Subtle Poster Right Turn	Camouflage Graffiti	Camouflage Art (LISA-CNN)	Camouflage Art (GTSRB-CNN)
5' 0°					
5' 15°					
10' 0°					
10' 30°					
40' 0°					
Targeted-Attack Success	100%	73.33%	66.67%	100%	80%

Physical-World Attack: Adversarial Patch

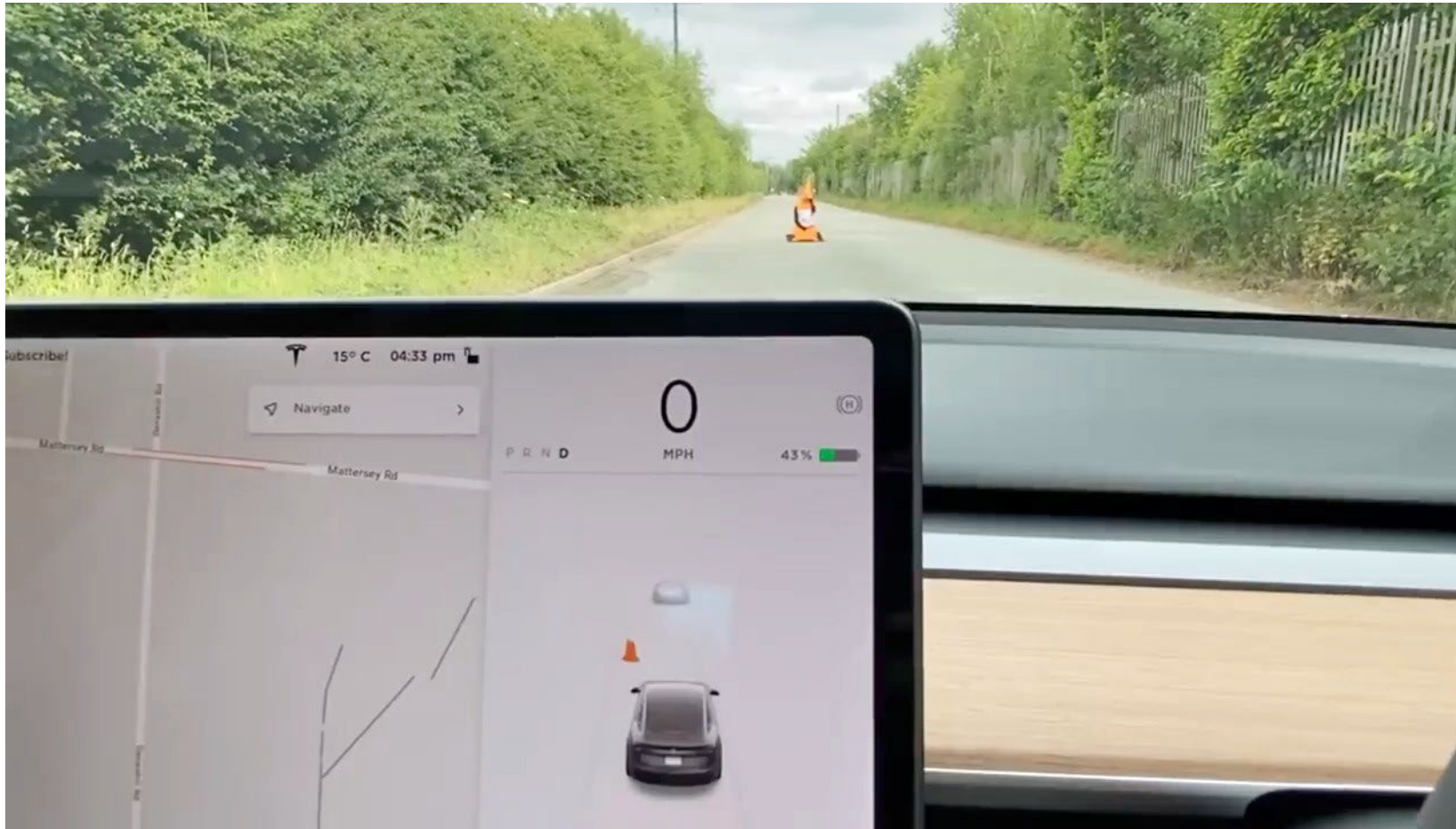
- Not only adversarial patch can fool a classifier, but also a SOTA detector
- An example of a person wearing an adversarial patch who cannot be detected by a YOLOv2 model
 - This can be used by intruders to get past security cameras



Thys et al. (2019) - Fooling automated surveillance cameras: adversarial patches to attack person detection

Physical-World Attack: Attack Tesla Autopilot

- A Tesla owner checks if the car can distinguish a person wearing a cover-up from a traffic cone



Physical-World Attack: Attack Waymo Autopilot



BUSINESS

Armed with traffic cones, protesters are immobilizing driverless cars

AUGUST 26, 2023 · 7:01 AM ET

By [Dara Kerr](#)



A Waymo driverless car gets coned in San Francisco.

Dara Kerr/NPR



Members of Safe Street Rebel place a cone on a self-driving Cruise car in San Francisco.
Josh Edelson/AFP via Getty Images

Two people dressed in dark colors and wearing masks dart into a busy street on a hill in San Francisco. One of them hauls a big orange traffic cone. They sprint toward a [driverless car](#) and quickly set the cone on the hood.

The vehicle's side lights burst on and start flashing orange. And then, it sits there immobile.

"All right, looks good," one of them says after making sure no one is inside. "Let's get out of here." They hop on e-bikes and pedal off.

All it takes to render the technology-packed self-driving car inoperable is a traffic cone. If all goes according to plan, it will stay there, frozen, until someone comes and removes it.

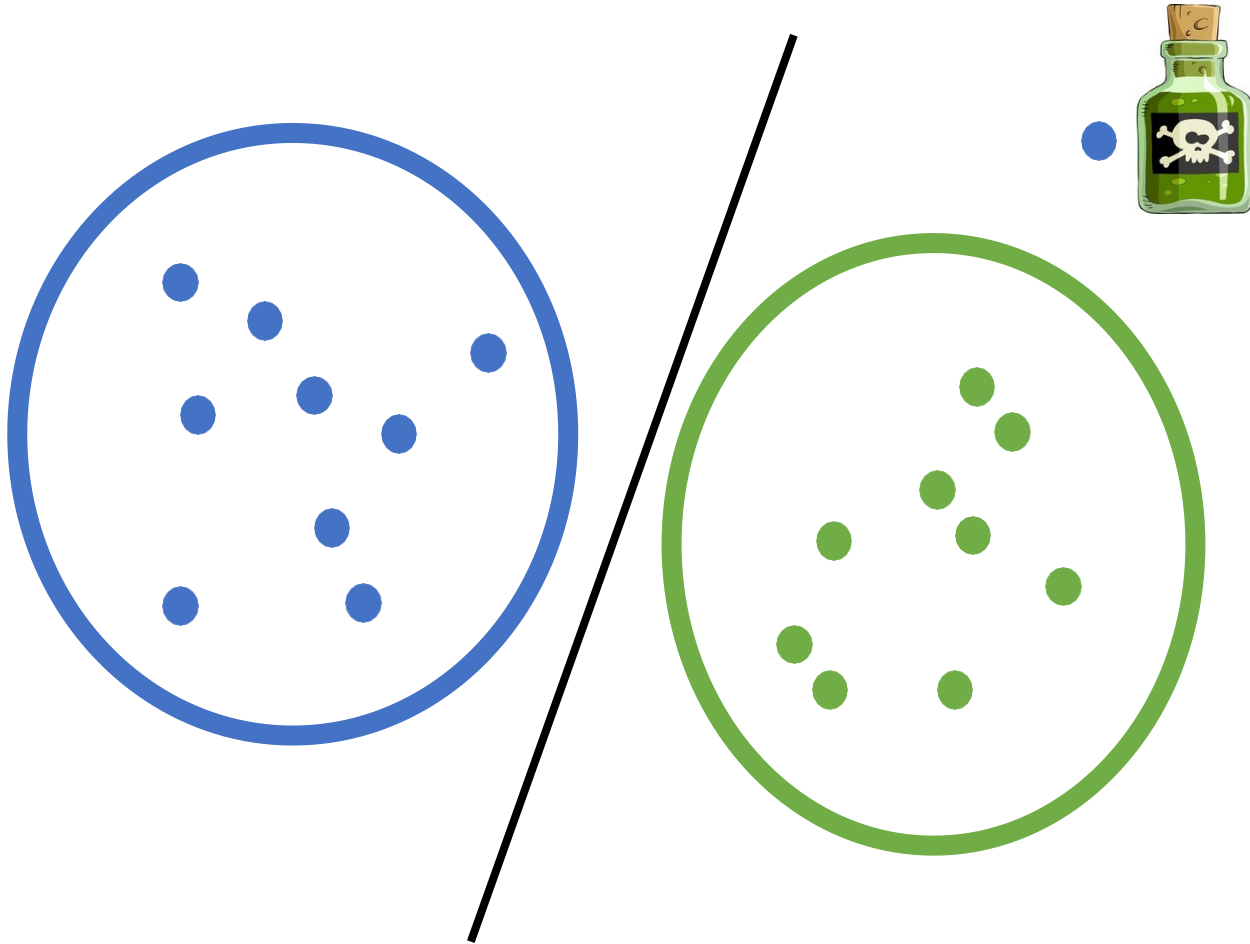
Atypical Poses can fool NNs



school bus 1.0 **garbage truck** 0.99 **punching bag** 1.0 **snowplow** 0.92

Data Poisoning

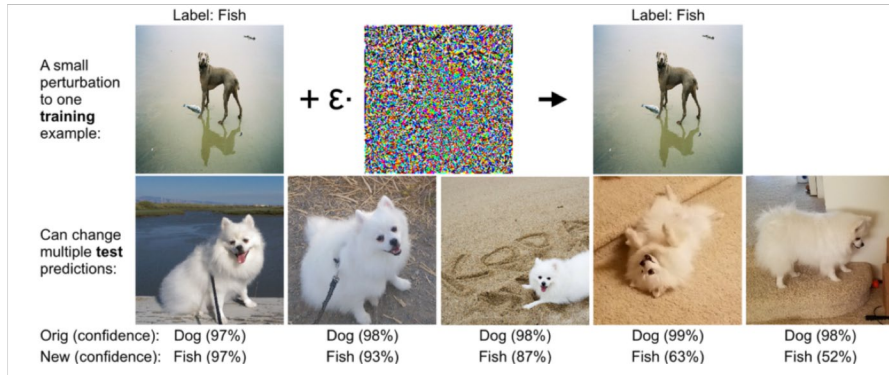
Goal: Maintain training accuracy but hamper generalization



Data Poisoning

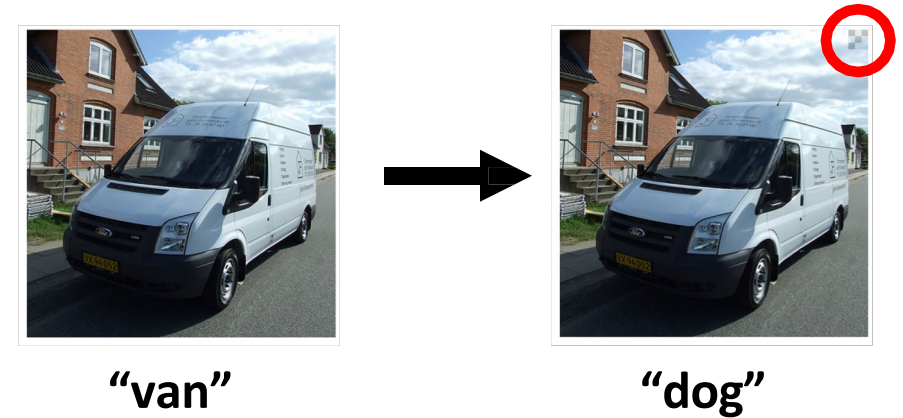
classification of **specific** inputs

Goal: Maintain training accuracy but hamper generalization



[Koh Liang 2017]: Can manipulate **many** predictions with a **single** “poisoned” input

But: This gets (much) worse



[Gu Dolan-Gavitt Garg 2017][Turner Tsipras **M** 2018]:
Can plant an **undetectable backdoor** that gives an almost **total** control over the model

You don't even need poisonous samples.

Re-ordering training batches of clean data → failures

Mole Recruitment: Poisoning of Image Classifiers via Selective Batch Sampling

Ethan Wisdom Tejas Gokhale Chaowei Xiao Yezhou Yang

Arizona State University

{ewisdom, tgokhale, cxiao17, yz.yang}@asu.edu

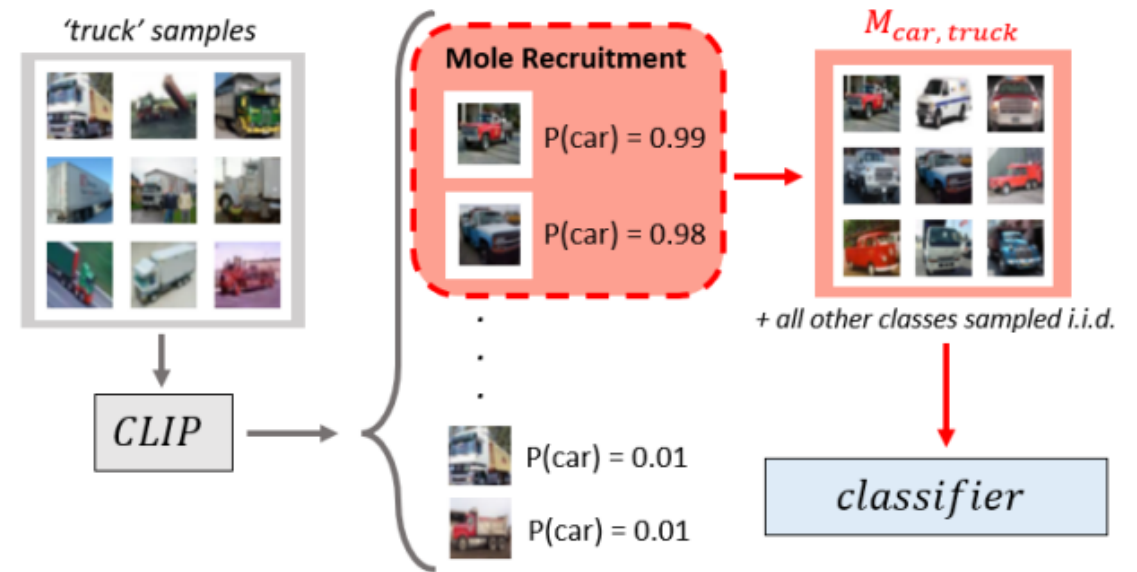


Figure 1. Using an external model such as CLIP, the distribution of the confounding class (truck) samples is examined with respect to their softmax probabilities of the attacked class (car). The samples with the highest probability are used to train an image classifier, which confounds the classifier's ability to distinguish between the attacked and confounding classes.





Handwritten notes ...

