

Part 2 – Filtering

Preface to Part 2 Response

The prompt describes a scenario in which a movie theater worker determines the popularity of a movie based on whether the popcorn machine is empty and the number of nights that the movie has been shown (Matuszek, 2024). A diagram of the dependency relationship network and conditional probability tables can be found in Figure 2 below.

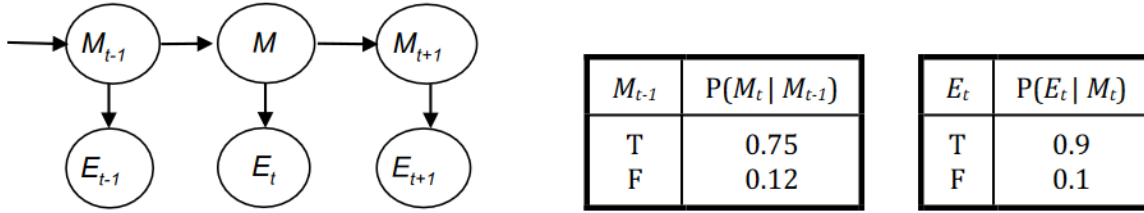


Figure 2: Dependency network and conditional probability tables for Homework 3, Part 2. (Matuszek, 2024)

Response to Part 2, Question 4

The prompt requests the calculation of the probability that a movie is popular on day 3 based on finding a full popcorn hopper on day 2 and finding an empty popcorn hopper on day 3 (Matuszek, 2024).

First, one must translate the prompt into a conditional probability statement $P(M_3 | \overline{E}_2, E_3)$ where M_3 represents a movie being popular on day 3, \overline{E}_2 representing finding a full hopper on day 2, and E_3 representing finding an empty hopper on day 3.

Given the relationship between the popularity of a movie on a given day and the state of the popcorn hopper for the same day, one can calculate the desired probability using a sequence of transition and sensor updates to the initial state of movie popularity.

Movies are claimed to have a probability of being popular at 75%. This can be represented as a vector

$$\langle P(M_0), P(\overline{M}_0) \rangle = \langle 0.75, 0.25 \rangle$$

Day 1 Transition Update

One can update the movie popularity probabilities using a transition update from day 0 to day 1.

$$\begin{aligned} \langle P(M_1), P(\overline{M}_1) \rangle &= \sum_{m_0 \in \{M_0, \overline{M}_0\}} \langle P(M_1 | m_0), P(\overline{M}_1 | m_0) \rangle \cdot P(m_0) \\ \langle P(M_1), P(\overline{M}_1) \rangle &= \langle P(M_1 | M_0), P(\overline{M}_1 | M_0) \rangle \cdot P(M_0) + \langle P(M_1 | \overline{M}_0), P(\overline{M}_1 | \overline{M}_0) \rangle \cdot P(\overline{M}_0) \end{aligned}$$

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Using values from the state transition tables and the prior probabilities, one can substitute values for $P(M_1|M_0)$, $P(\overline{M}_1|M_0)$, $P(M_1|\overline{M}_0)$, $P(\overline{M}_1|\overline{M}_0)$, $P(M_0)$, and $P(\overline{M}_0)$.

$$\begin{aligned}\langle P(M_1), P(\overline{M}_1) \rangle &= \langle 0.75, 0.25 \rangle \cdot 0.75 + \langle 0.12, 0.88 \rangle \cdot 0.25 \\ \langle P(M_1), P(\overline{M}_1) \rangle &= \langle 0.5925, 0.4075 \rangle\end{aligned}$$

Since the state of the hopper is not known for day 1, there is no sensor update to these prior probabilities for $\langle P(M_1), P(\overline{M}_1) \rangle$. Therefore, $\langle P(M_1|e_1), P(\overline{M}_1|e_1) \rangle = \langle P(M_1), P(\overline{M}_1) \rangle$.

Day 2 Transition Update

One can update the movie popularity probabilities using a transition update from day 1 to day 2. Note that some looseness in notation is used: $P(m_1|e_1)$ in this context represents the prior probability from day 1 given all known evidence up to day 1.

$$\begin{aligned}\langle P(M_2), P(\overline{M}_2) \rangle &= \sum_{m_1 \in \{M_1, \overline{M}_1\}} \langle P(M_2|m_1), P(\overline{M}_2|m_1) \rangle \cdot P(m_1|e_1) \\ \langle P(M_2), P(\overline{M}_2) \rangle &= \langle P(M_2|M_1), P(\overline{M}_2|M_1) \rangle \cdot P(M_1|e_1) + \langle P(M_2|\overline{M}_1), P(\overline{M}_2|\overline{M}_1) \rangle \cdot P(\overline{M}_1|e_1)\end{aligned}$$

Using values from the state transition tables and the prior probabilities, one can substitute values for $P(M_2|M_1)$, $P(\overline{M}_2|M_1)$, $P(M_2|\overline{M}_1)$, $P(\overline{M}_2|\overline{M}_1)$, $P(M_1)$, and $P(\overline{M}_1)$.

$$\begin{aligned}\langle P(M_2), P(\overline{M}_2) \rangle &= \langle 0.75, 0.25 \rangle \cdot 0.5925 + \langle 0.12, 0.88 \rangle \cdot 0.4075 \\ \langle P(M_2), P(\overline{M}_2) \rangle &= \langle 0.493275, 0.506725 \rangle\end{aligned}$$

Day 2 Sensor Update

Evidence on day 2 shows the popcorn hopper is full for that day. This can be integrated into the prior probability for day 2 using a sensor update.

$$\langle P(M_2|\overline{E}_2), P(\overline{M}_2|\overline{E}_2) \rangle = \alpha \cdot \langle P(\overline{E}_2|M_2), P(\overline{E}_2|\overline{M}_2) \rangle \cdot \langle P(M_2), P(\overline{M}_2) \rangle$$

Using values from the sensor tables and the prior probabilities, one can substitute values for $P(\overline{E}_2|M_2)$, $P(\overline{E}_2|\overline{M}_2)$, $P(M_2)$, and $P(\overline{M}_2)$.

$$\begin{aligned}\langle P(M_2|\overline{E}_2), P(\overline{M}_2|\overline{E}_2) \rangle &= \alpha \cdot \langle 0.1, 0.9 \rangle \cdot \langle 0.493275, 0.506725 \rangle \\ \langle P(M_2|\overline{E}_2), P(\overline{M}_2|\overline{E}_2) \rangle &= \alpha \cdot \langle 0.0493275, 0.4560525 \rangle\end{aligned}$$

Using an alpha value $\alpha = 1/0.50538$, one can normalize the probabilities of $P(M_2|\overline{E}_2)$ and $P(\overline{M}_2|\overline{E}_2)$.

$$\langle P(M_2|\overline{E}_2), P(\overline{M}_2|\overline{E}_2) \rangle \approx \langle 0.0976, 0.9024 \rangle$$

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Day 3 Transition Update

One can update the movie's popularity probabilities using a transition update from day 2 to day 3. Note that some looseness in notation is used: $P(m_2|e_{1:2})$ in this context represents the prior probability from day 2 given all known evidence up to day 2.

$$\begin{aligned}\langle P(M_3), P(\overline{M}_3) \rangle &= \sum_{m_2 \in \{M_2, \overline{M}_2\}} \langle P(M_3|m_2), P(\overline{M}_3|m_2) \rangle \cdot P(m_2|e_{1:2}) \\ \langle P(M_3), P(\overline{M}_3) \rangle &= \langle P(M_3|M_2), P(\overline{M}_3|M_2) \rangle \cdot P(M_2|e_{1:2}) + \langle P(M_3|\overline{M}_2), P(\overline{M}_3|\overline{M}_2) \rangle \cdot P(\overline{M}_2|e_{1:2})\end{aligned}$$

Using values from the state transition tables and the prior probabilities, one can substitute values for $P(M_3|M_2)$, $P(\overline{M}_3|M_2)$, $P(M_3|\overline{M}_2)$, $P(\overline{M}_3|\overline{M}_2)$, $P(M_2|e_{1:2})$, and $P(\overline{M}_2|e_{1:2})$.

$$\begin{aligned}\langle P(M_3), P(\overline{M}_3) \rangle &= \langle 0.75, 0.25 \rangle \cdot 0.0976 + \langle 0.12, 0.88 \rangle \cdot 0.9024 \\ \langle P(M_3), P(\overline{M}_3) \rangle &= \langle 0.181488, 0.818512 \rangle\end{aligned}$$

Day 3 Sensor Update

Evidence on day 3 shows the popcorn hopper is empty for that day. This can be integrated into the prior probability for day 2 using a sensor update.

$$\langle P(M_3|E_3), P(\overline{M}_3|E_3) \rangle = \alpha \cdot \langle P(E_3|M_3), P(E_3|\overline{M}_3) \rangle \cdot \langle P(M_3), P(\overline{M}_3) \rangle$$

Using values from the sensor tables and the prior probabilities, one can substitute values for $P(E_3|M_3)$, $P(E_3|\overline{M}_3)$, $P(M_3)$, and $P(\overline{M}_3)$.

$$\begin{aligned}\langle P(M_3|E_3), P(\overline{M}_3|E_3) \rangle &= \alpha \cdot \langle 0.9, 0.1 \rangle \cdot \langle 0.181488, 0.818512 \rangle \\ \langle P(M_3|E_3), P(\overline{M}_3|E_3) \rangle &= \alpha \cdot \langle 0.1633392, 0.0818512 \rangle\end{aligned}$$

Using an alpha value $\alpha = 1/0.2451904$, one can normalize the probabilities of $P(M_3|E_3)$ and $P(\overline{M}_3|E_3)$.

$$\langle P(M_3|E_3), P(\overline{M}_3|E_3) \rangle \approx \langle 0.6662, 0.3338 \rangle$$

Therefore, the probability that a movie was popular on day 3 given a full hopper on day 2 and an empty hopper on day 3 is ~66.62%.