



Search in Python

Chapter 3

Today's topics

- AIMA Python code
- What it does
- How to use it
- Worked example: water jug program



Install AIMA Python ?

- [Aimacode](#) is a great github repo of python code linked to the AIMA book
- It's not available for pip installing 😞
 - Pete Norvig's recommendation
- One workaround is to:
 - Clone the repo on your computer and follow the instructions in its [readme file](#)
 - Add the directory to your [PYTHONPATH](#) environment variable

Two Water Jugs Problem



- Given two water jugs, J1 and J2, with capacities C1 and C2 and initial amounts W1 and W2, find actions to end up with amounts W1' and W2' in the jugs
- Example problem:
 - We have a 5 gallon and a 2 gallon jug
 - Initially both are full
 - We want to end up with exactly one gallon in J2 and don't care how much is in J1

search.py

- Defines a *Problem* class for a search problem
- Has functions to perform various kinds of search given an instance of a *Problem*, e.g., breadth first, depth first, hill climbing, A*, ...
- *InstrumentedProblem* subclasses *Problem* and is used with *compare_searchers* for evaluation
- To use for WJP: (1) decide how to represent the WJP, (2) define *WJP* as a subclass of *Problem* and (3) provide methods to (a) create a WJP instance, (b) compute successors and (c) test for a goal

Example: Water Jug Problem



Given full 5-gal. jug
and empty 2-gal. jug,
fill 2-gal jug with one
gallon

- State = (x,y) , where x is water in jug 1; y is water in jug 2
- Initial State = $(5,0)$
- Goal State = $(-1,1)$, where -1 means any amount

Action table

Name	Cond.	Transition	Effect
dump1	$x > 0$	$(x,y) \rightarrow (0,y)$	Empty Jug 1
dump2	$y > 0$	$(x,y) \rightarrow (x,0)$	Empty Jug 2
pour_1_2	$x > 0$ & $y < C2$	$(x,y) \rightarrow (x-D, y+D)$ $D = \min(x, C2-y)$	Pour from Jug 1 to Jug 2
pour_2_1	$y > 0$ & $X < C1$	$(x,y) \rightarrow (x+D, y-D)$ $D = \min(y, C1-x)$	Pour from Jug 2 to Jug 1

Two Water Jugs Problem



Given J1 and J2 with capacities C1 and C2 and initial amounts W1 and W2, find actions to end up with W1' and W2' in jugs

State Representation

State = (x,y) , where x & y are water in J1 & J2

- Initial state = $(5,0)$
- Goal state = $(*,1)$, where $*$ is any amount

Operator table

Actions	Cond.	Transition	Effect
Empty J1	—	$(x,y) \rightarrow (0,y)$	Empty J1
Empty J2	—	$(x,y) \rightarrow (x,0)$	Empty J2
2to1	$x \leq 3$	$(x,2) \rightarrow (x+2,0)$	Pour J2 into J1
1to2	$x \geq 2$	$(x,0) \rightarrow (x-2,2)$	Pour J1 into J2
1to2part	$y < 2$	$(1,y) \rightarrow (0,y+1)$	Pour J1 into J2 until full

Our WJ problem class



```
class WJ(Problem):  
    def __init__(self, capacities=(5,2), initial=(5,0), goal=(0,1)):  
        self.capacities = capacities  
        self.initial = initial  
        self.goal = goal  
  
    def goal_test(self, state): # returns True iff state is a goal state  
        g = self.goal  
        return (state[0] == g[0] or g[0] == -1 ) and  
                (state[1] == g[1] or g[1] == -1)  
  
    def __repr__(self): # returns string representing the object  
        return f"WJ({self.capacities},{self.initial},{self.goal}"
```

Note: f-string

Our WJ problem class

```
def actions(self, state):
```

```
    """returns iterable with all state's legal actions"""
```

```
    (J1, J2) = state
```

```
    (C1, C2) = self.capacities
```

```
    if J1>0: yield ('dump', 1)
```

```
    if J2>0: yield ('dump', 2)
```

```
    if J2<C2 and J1>0: yield ('pour', 1, 2)
```

```
    if J1<C1 and J2>0: yield ('pour', 2, 1)
```

yield? See [here](#)

Actions returning a list

```
def actions(self, state):  
    (J1, J2) = state  
    (C1, C2) = self.capacities  
    legal = []  
    if J1>0: legal.append(('dump', 1))  
    if J2>0: legal.append(('dump', 2))  
    if J2<C2 and J1>0: legal.append(('pour', 1, 2))  
    if J1<C1 and J2>0: yield (('pour', 2, 1))  
    return legal
```

WJ problem class

```
def result(self, state, action):
    """ Given state and action, returns successor
        after doing action """
    if len(action) == 2:
        act, arg1 = action
    else:
        act, arg1, arg2 = action
    (J1, J2), (C1, C2) = state, self.capacities
    if act == 'dump':
        return (0, J2) if arg1 == 1 else (J1, 0)
    elif act == 'pour':
        if arg1 == 1:
            delta = min(J1, C2-J2)
            return (J1-delta, J2+delta)
        else:
            delta = min(J2, C1-J1)
            return (J1+delta, J2-delta)
```

Our WJ problem class

```
def h(self, node):  
    # heuristic function that estimates distance  
    # to a goal node  
    return 0 if self.goal_test(node.state) else 1
```

Solving a WJP

```
code> python
```

```
>>> from wj import *
```

```
# Import wj.py and search.py
```

```
>>> from aima3.search import *
```

```
>>> p1 = WJ((5,2), (5,2), ('*', 1))
```

```
# Create a problem instance
```

```
>>> p1
```

```
WJ((5, 2),(5, 2),('*', 1))
```

```
>>> answer = breadth_first_search(p1)
```

```
# Used the breadth 1st search function
```

```
>>> answer
```

```
# Will be None if the search failed or a
```

```
<Node (0, 1)>
```

```
# a goal node in the search graph if successful
```

```
>>> answer.path_cost
```

```
# The cost to get to every node in the search graph
```

```
6
```

```
# is maintained by the search procedure
```

```
>>> path = answer.path()
```

```
# A node's path is the best way to get to it from
```

```
>>> path
```

```
# the start node, i.e., a solution
```

```
[<Node (5, 2)>, <Node (5, 0)>, <Node (3, 2)>, <Node (3, 0)>, <Node (1, 2)>, <Node (1, 0)>, <Node (0, 1)>]
```

Comparing Search Algorithms Results

Uninformed searches: breadth_first_tree_search, breadth_first_search, depth_first_graph_search, iterative_deepening_search, depth_limited_search

- All but depth_limited_search are **sound** (i.e., solutions found are correct)
- Not all are **complete** (i.e., can find all solutions)
- Not all are **optimal** (find best possible solution)
- Not all are **efficient**
- AIMA code has a comparison function

Comparing Search Algorithms Results

```
HW2> python
```

```
Python 2.7.6 |Anaconda 1.8.0 (x86_64)| ...
```

```
>>> from wj import *
```

```
>>> searchers=[breadth_first_search, depth_first_graph_search,  
iterative_deepening_search]
```

```
>>> compare_searchers([WJ((5,2), (5,0), (0,1))], ['SEARCH ALGORITHM',  
'successors/goal tests/states generated/solution'], searchers)
```

```
SEARCH ALGORITHM      successors/goal tests/states generated/solution
```

```
breadth_first_search  < 8/ 9/ 16/(0, >
```

```
depth_first_graph_search < 5/ 6/ 12/(0, >
```

```
iterative_deepening_search < 35/ 61/ 57/(0, >
```

```
>>>
```

The Output

```
hhw2> python wjtest.py -s 5 0 -g 0 1
```

```
Solving WJ((5, 2),(5, 0),(0, 1)
```

```
breadth_first_tree_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
breadth_first_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
depth_first_graph_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
iterative_deepening_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
astar_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
SUMMARY: successors/goal tests/states generated/solution
```

```
breadth_first_tree_search < 25/ 26/ 37/(0, >
```

```
breadth_first_search < 8/ 9/ 16/(0, >
```

```
depth_first_graph_search < 5/ 6/ 12/(0, >
```

```
iterative_deepening_search < 35/ 61/ 57/(0, >
```

```
astar_search < 8/ 10/ 16/(0, >
```